



Generating an InSAR DEM using ASF software tools

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Outline

- AKDEM production system
- SAR interferometric processing chain
 - general setup
 - examples

InSAR DEM generation



AKDEM production system

- driver program runs processing chain from data ingest until geocoded digital elevation model
- allows STF, RAW and SLC data
- runs from configuration file
- allows definition of default values

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Configuration file

AKDEM project: Configuration file

[General]

reference dem = /3dsar2/tlogan/dem/alaska_dem.img

base name = 57_23592_3919

log file = 1

quiet = 1

processors = 8

data type = STF

lat begin = 63.500

lat end = 64.500

coregistration = AUTOMATIC

maximum offset = 3

default values = /3dsar2/tlogan/default_values2

status = new

[Master image]

path = /3dsar2/akdem/tracks/57_tape1

data file = e2_3919.000

metadata file = e2_3919.000.par

[Slave image]

path = /3dsar2/akdem/tracks/57_other

data file = e1_23592.000

metadata file = e1_23592.000.par

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Default values

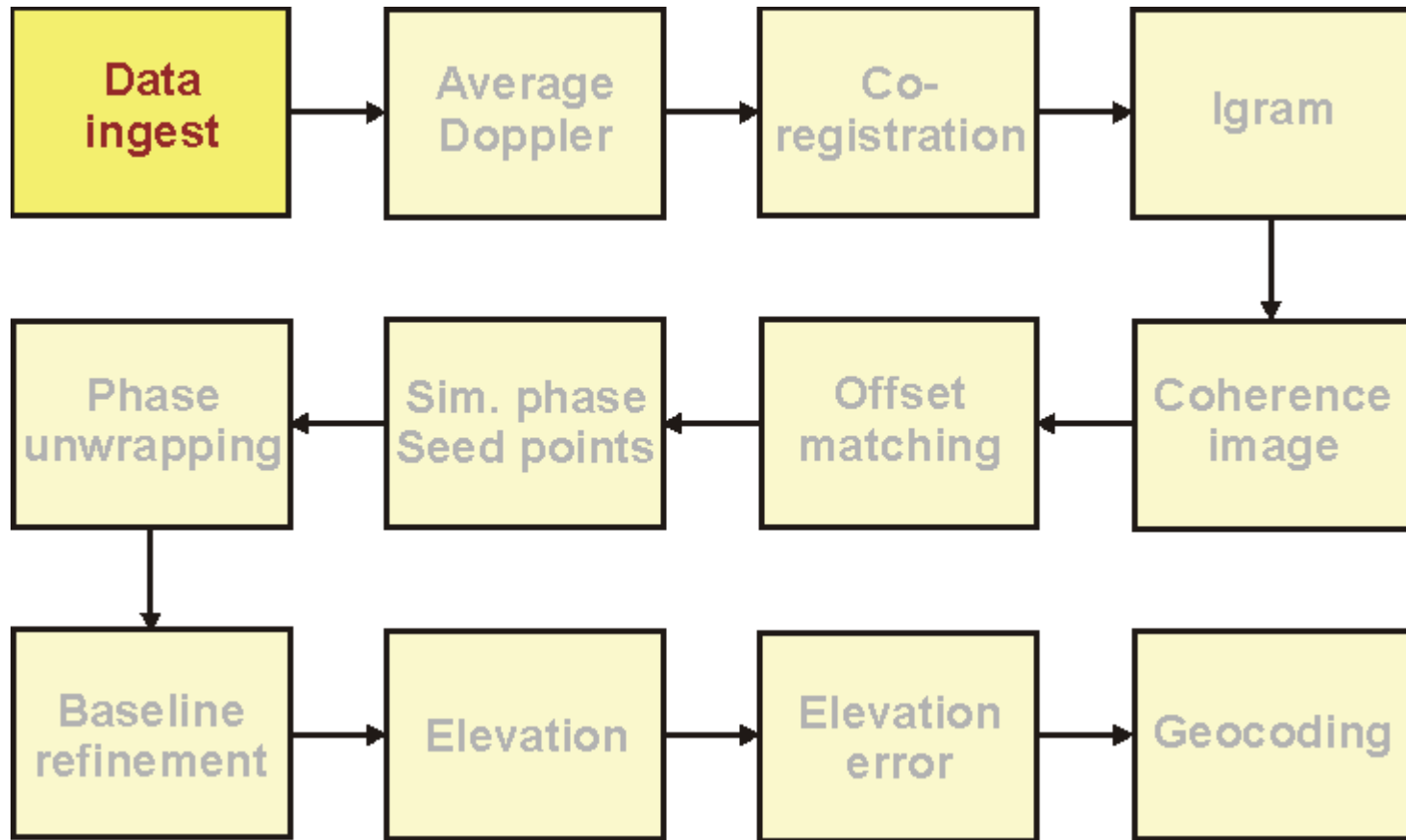
reference dem = /3dsar2/tlogan/dem/alaska_fixed.img
log = 1
quiet = 1
processors = 8
data type = STF
coregistration = AUTOMATIC
maximum offset = 3
precise master = /3dsar2/tlogan/PRC/ERS2
precise slave = /3dsar2/tlogan/PRC/ERS1
minimum coherence = 0.3
phase unwrapping = snaphu_v2
projection file = /3dsar2/tlogan/albers.proj
projection key = albers
pixel spacing = 20

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InSAR processing

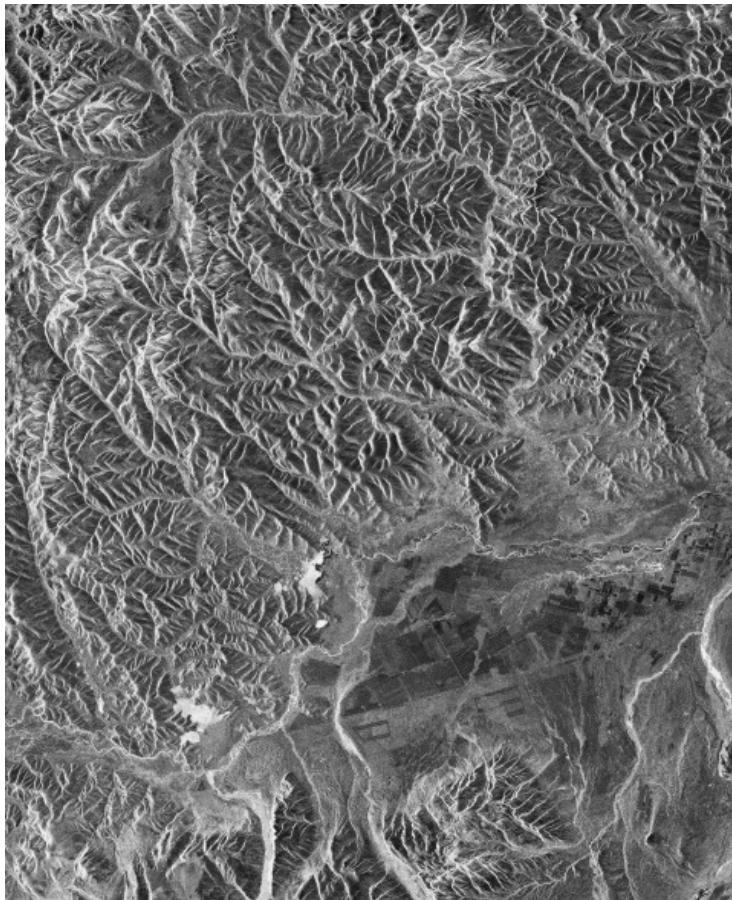
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Data ingest

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64.5°

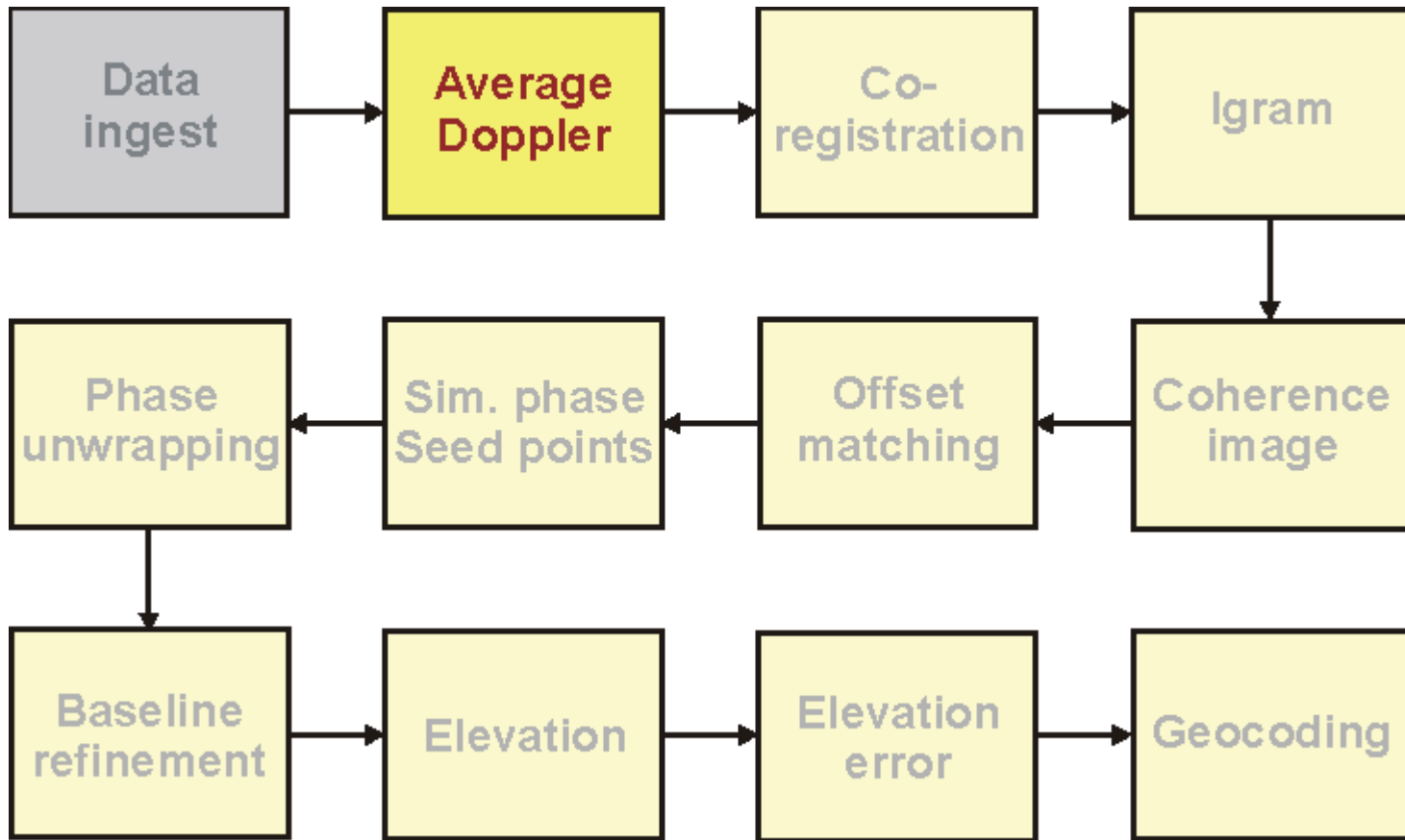
- ingest of STF data
- can handle precision state vectors for ERS data
- allows latitude constraint

63.5°



InSAR processing

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Average Doppler

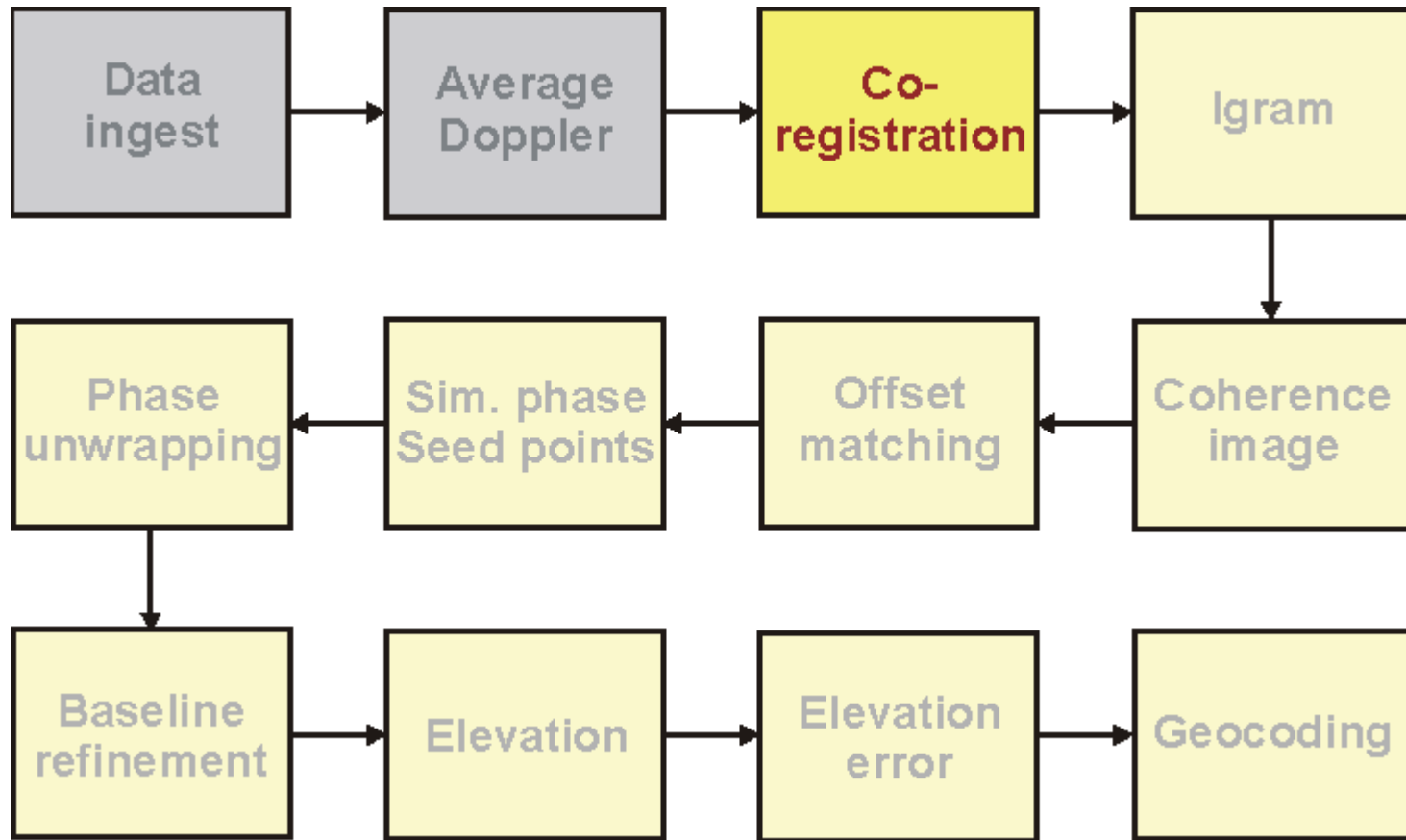
- getting both images into the same geometry
- works fine for ERS imagery
- Radarsat imagery requires zero Doppler processing (currently under development)

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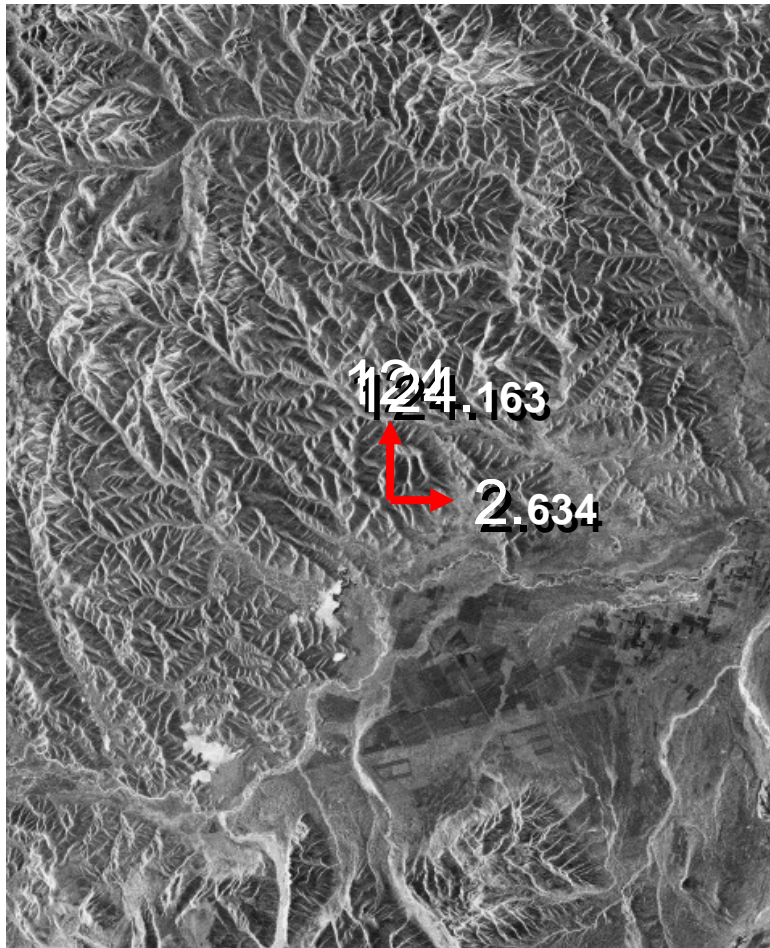
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Co-registration

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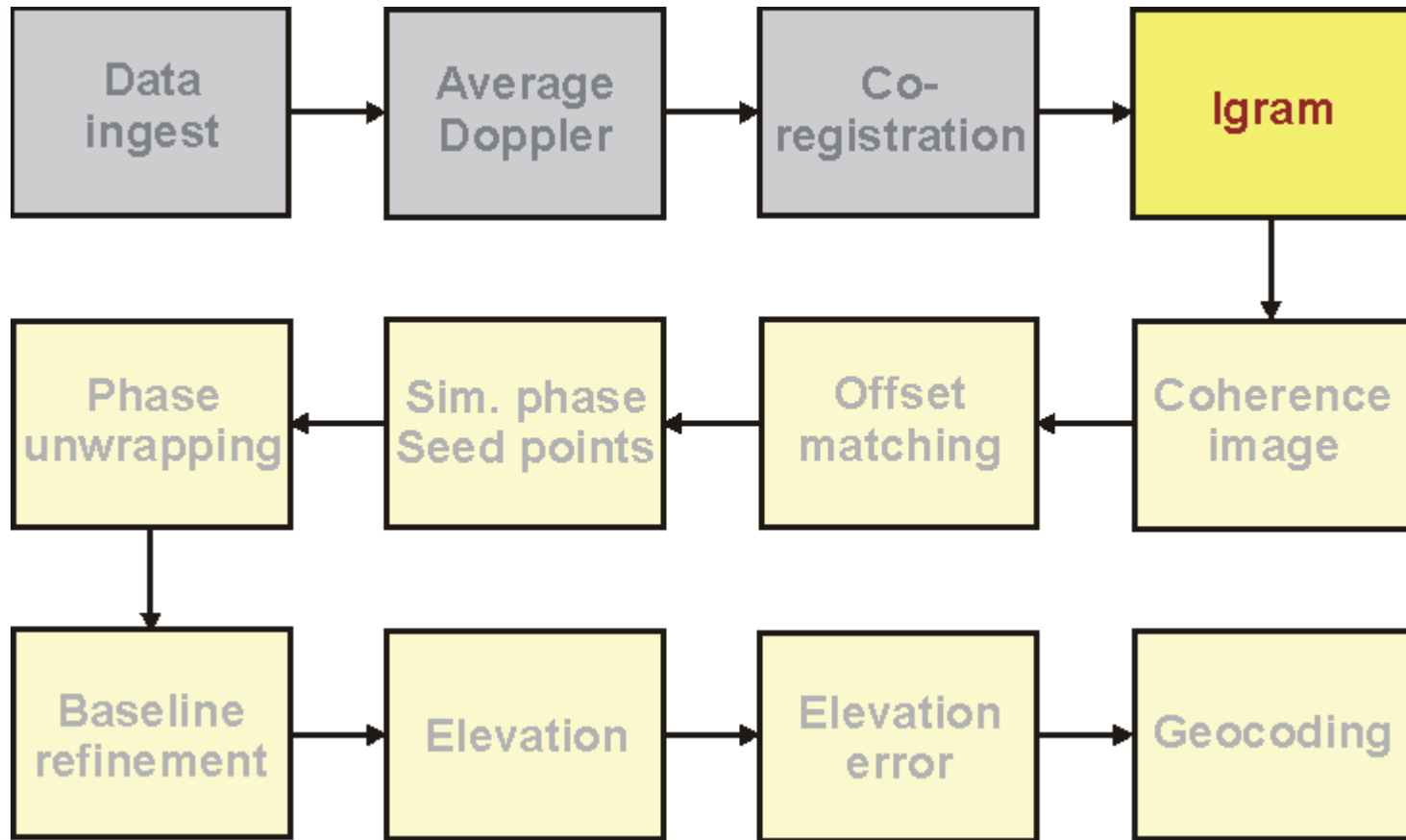


- initial offset estimated from state vectors (pixels)
- fine co-registration for sub-pixel accuracy
- baseline estimate as side product
 $B_n = -61.829628$
 $B_p = 19.505440$
- exit condition with maximum offset (default 3 pixels)



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Interferogram

- single-look interferogram
- color-coded multilooked interferogram

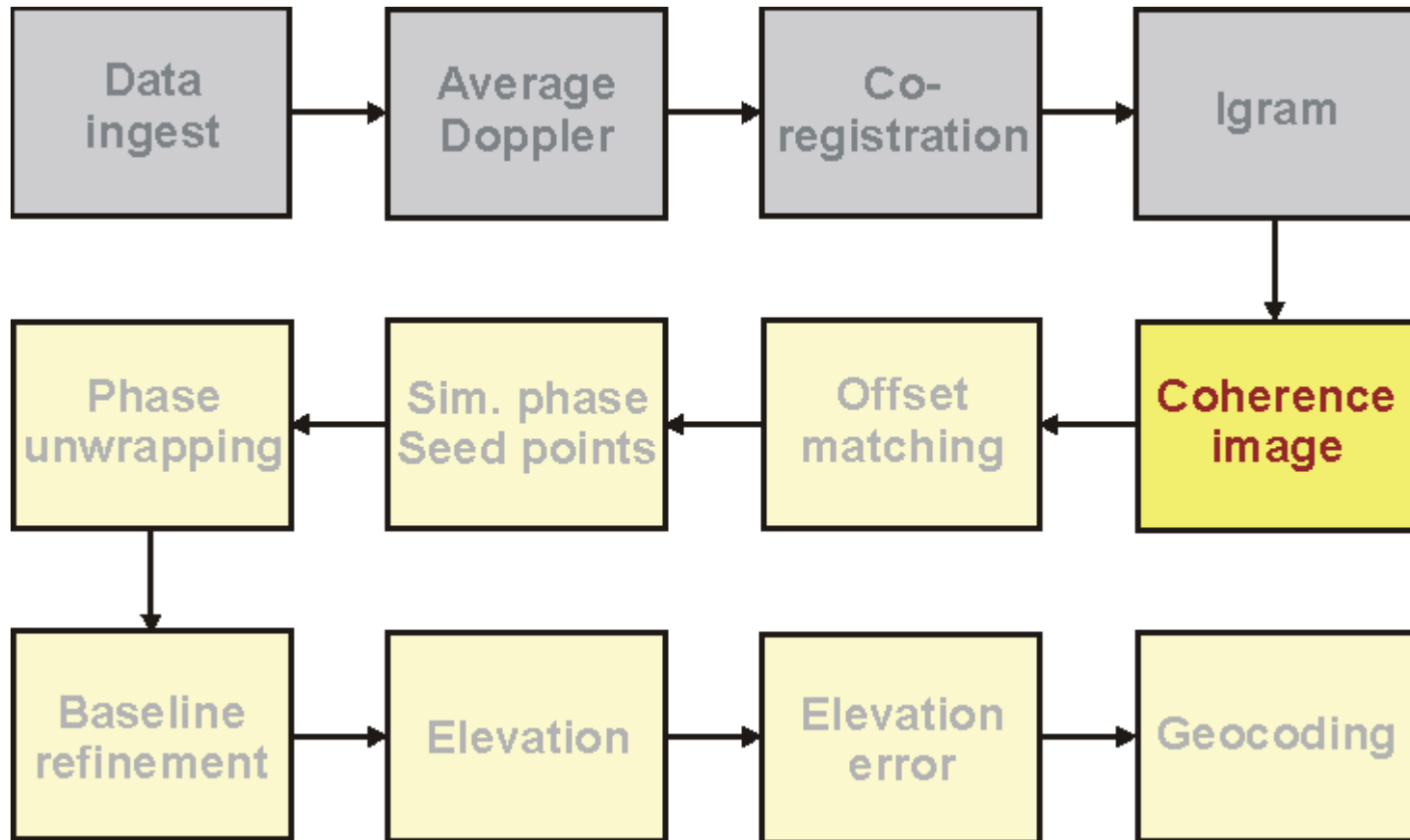


InSAR DEM generation



InSAR processing

InSAR DEM generation





Coherence image

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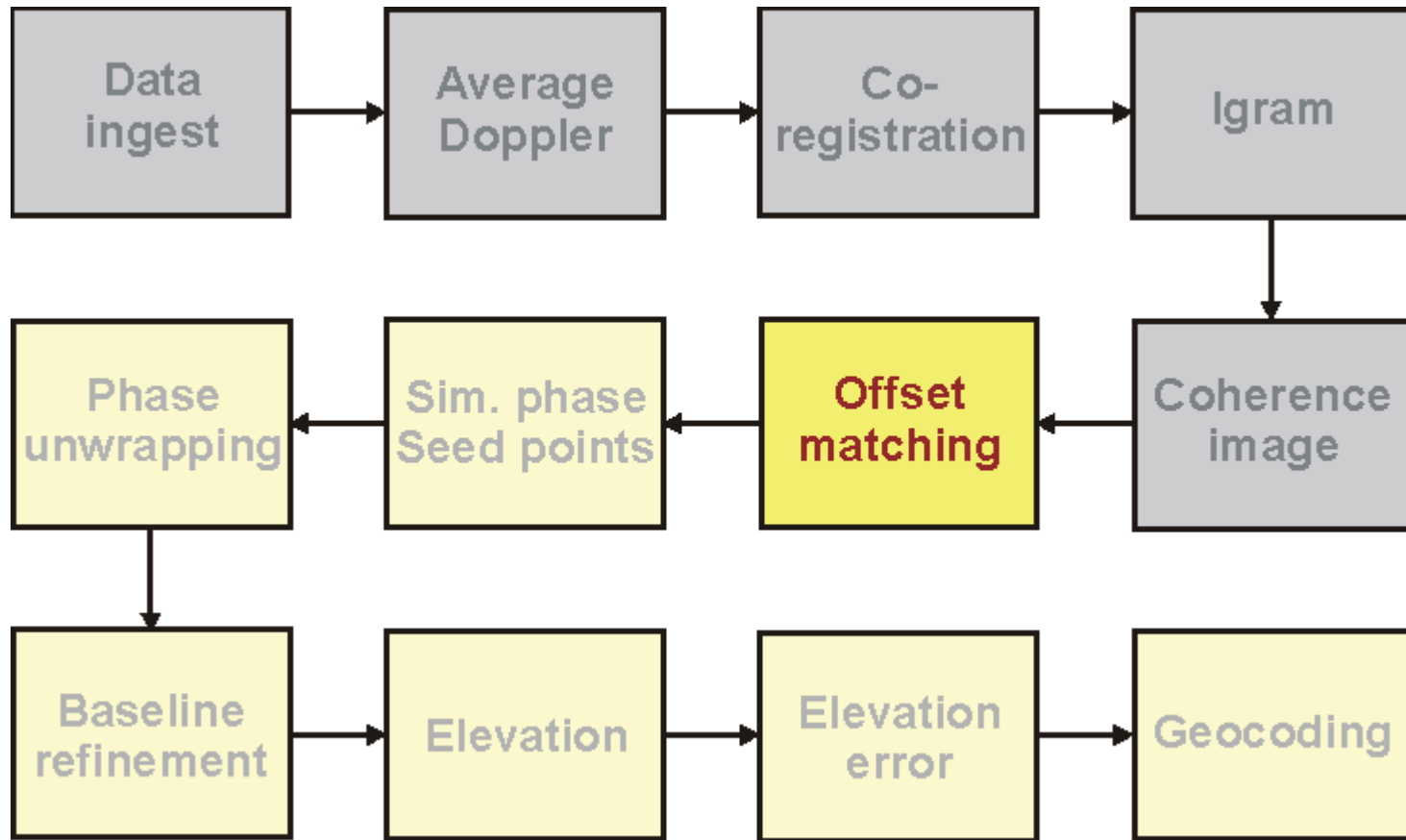


- exit condition with minimum coherence level (default value: 0.3)
- statistics
 - maximum: 0.975
 - average: 0.747



InSAR processing

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Offset matching

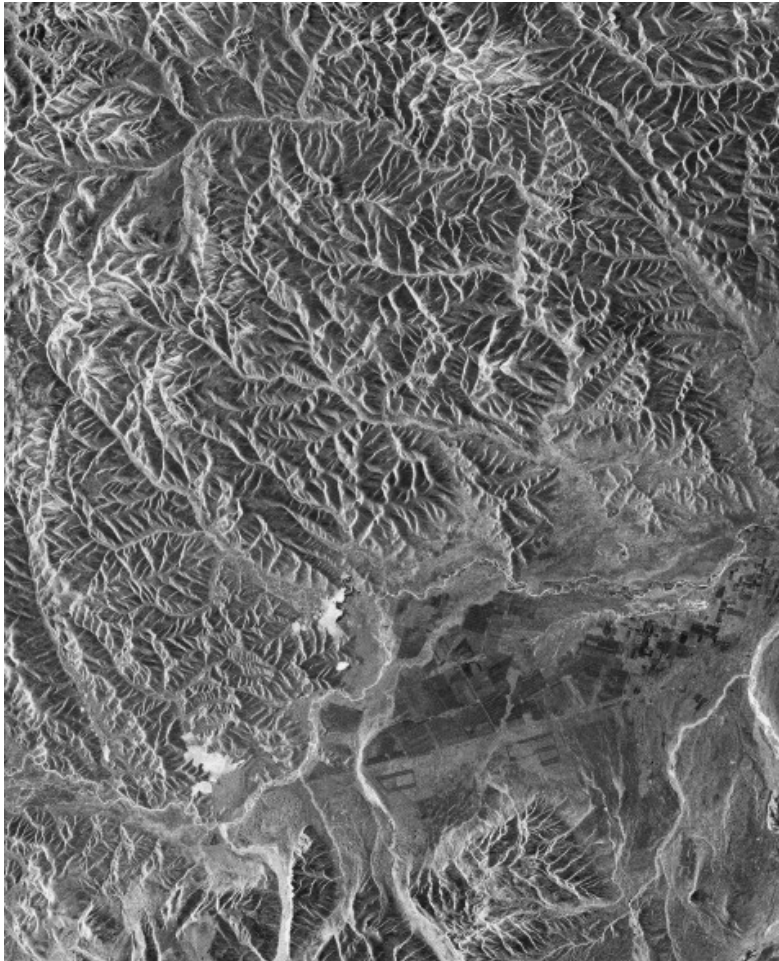
- improves geolocation by refining shifts in time and range
- iterative process
- matches real and simulated amplitude (derived from reference DEM) until no offset can be measured

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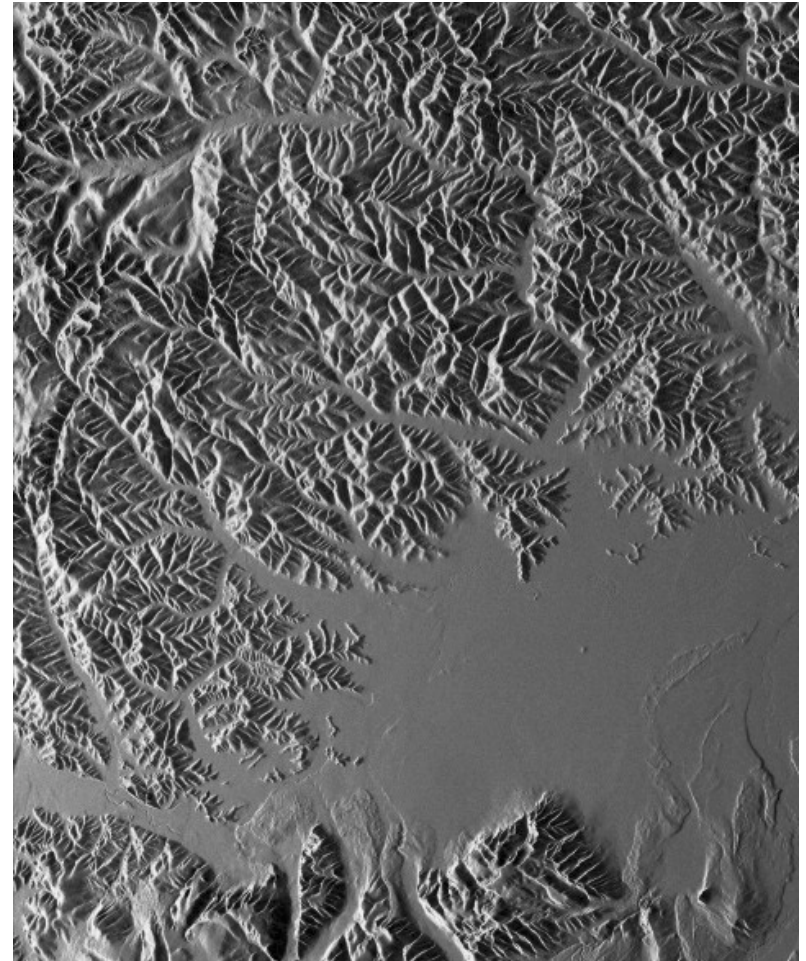


Offset matching

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real amplitude

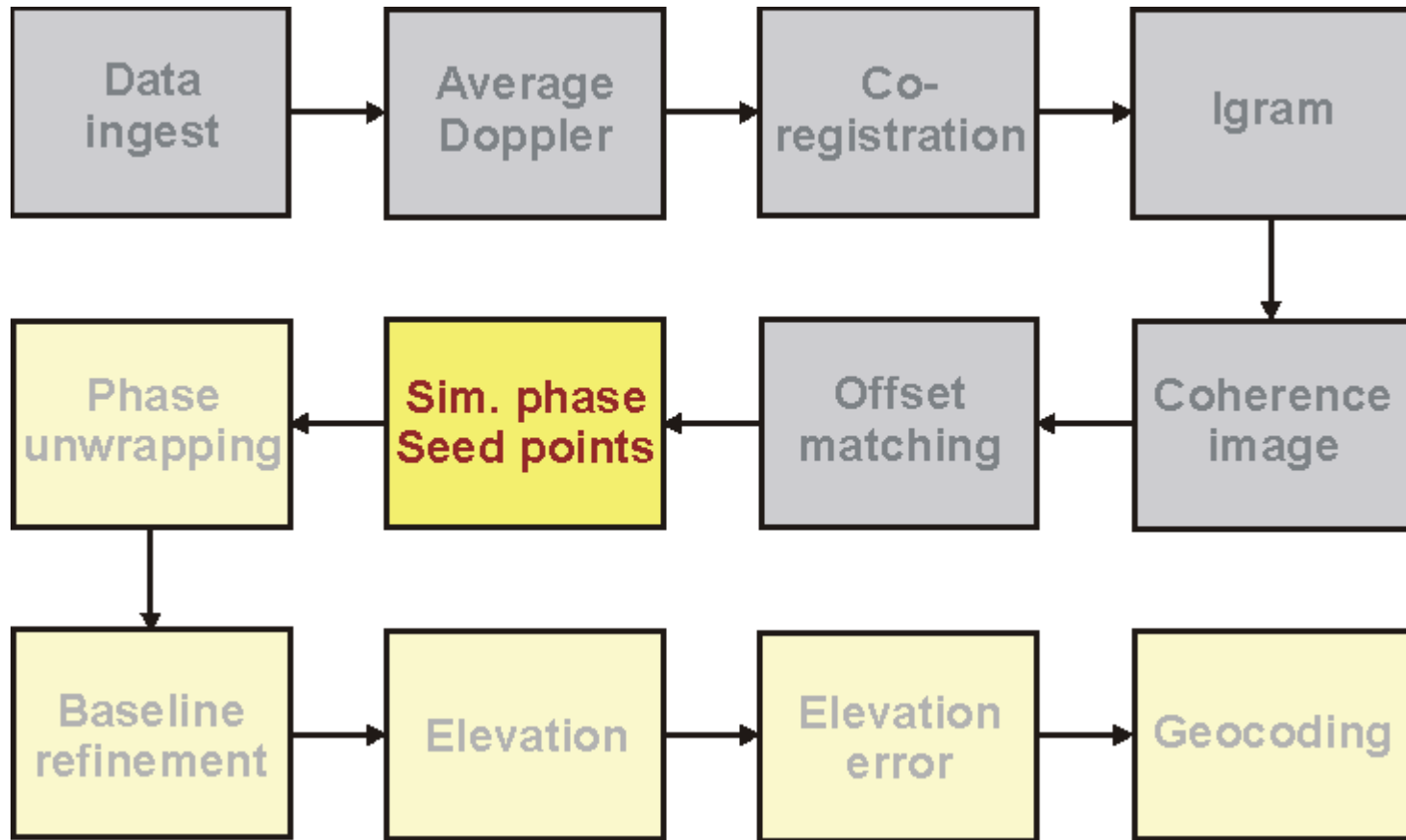


simulated amplitude



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Simulated phase / seeds points

- derived from reference DEM
- simulated phase
 - used for removal of topographic phase (optional)
- seed points
 - equally distributed
 - selection criteria: minimum slope in reference DEM
 - potential seed points: 10000
 - final number of seed points: 2321

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Seed point distribution

```

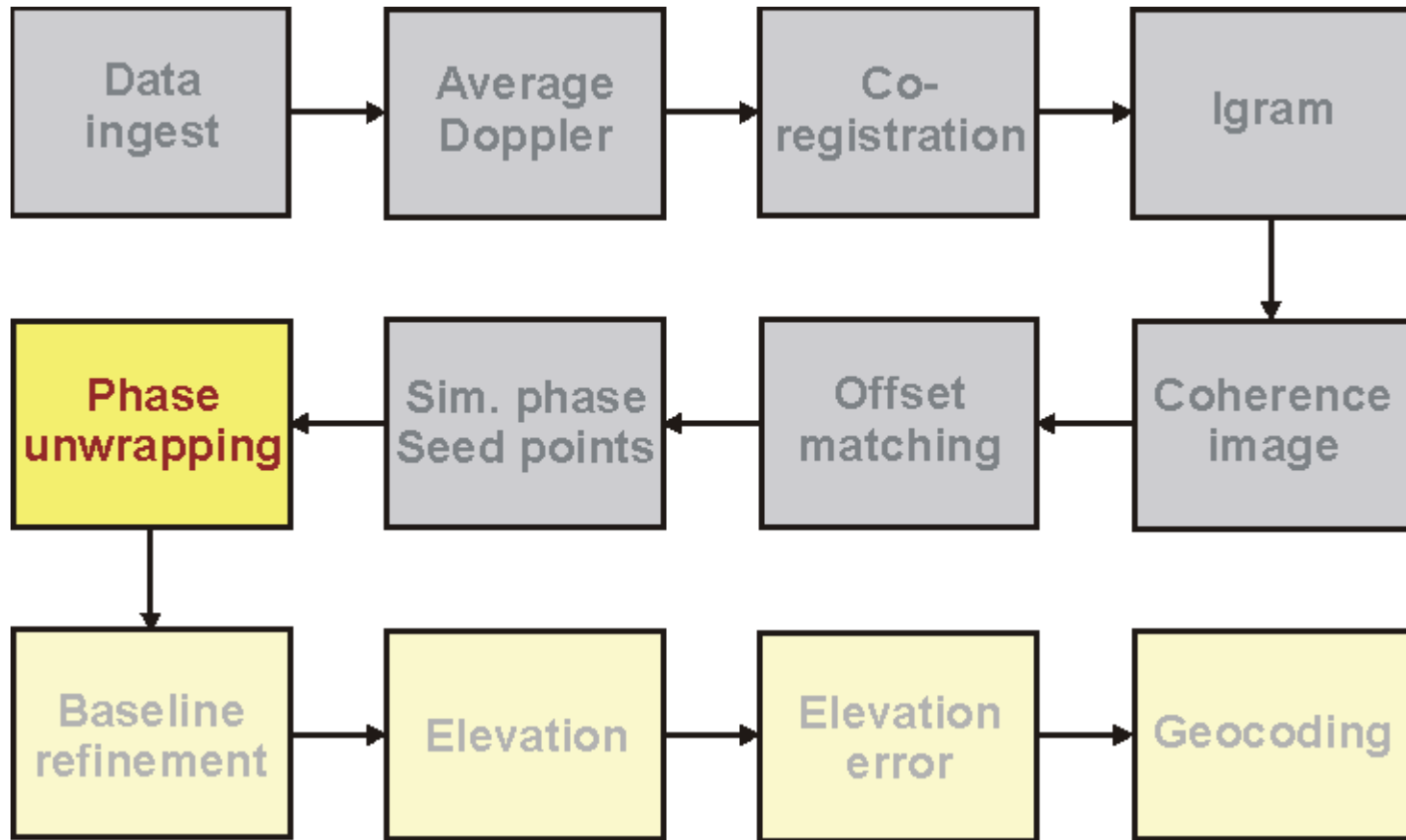
X  XXX   X  XXX  XX
   XXXXX           XXX
  XX      XXX   XX
   X X           XX X X
             X  XX   XX
             X  X  XX XX
               XXXXXXXXX
X  XX      XXXXXXXX
  XXXXXXXXXXXXXXXXXXXX
X  XXXXXXXXXXXXXXXXXXXX
   XXX XXXXXXXXXXXXXX
XXXXXXXXXXXXXXXXXXXXX
XXXXXXXXXXXXXXXXXXXXX
XX  XXXXXX   XXXX
XX  XXXXXX   XXXX
  
```

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InSAR processing

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Phase unwrapping

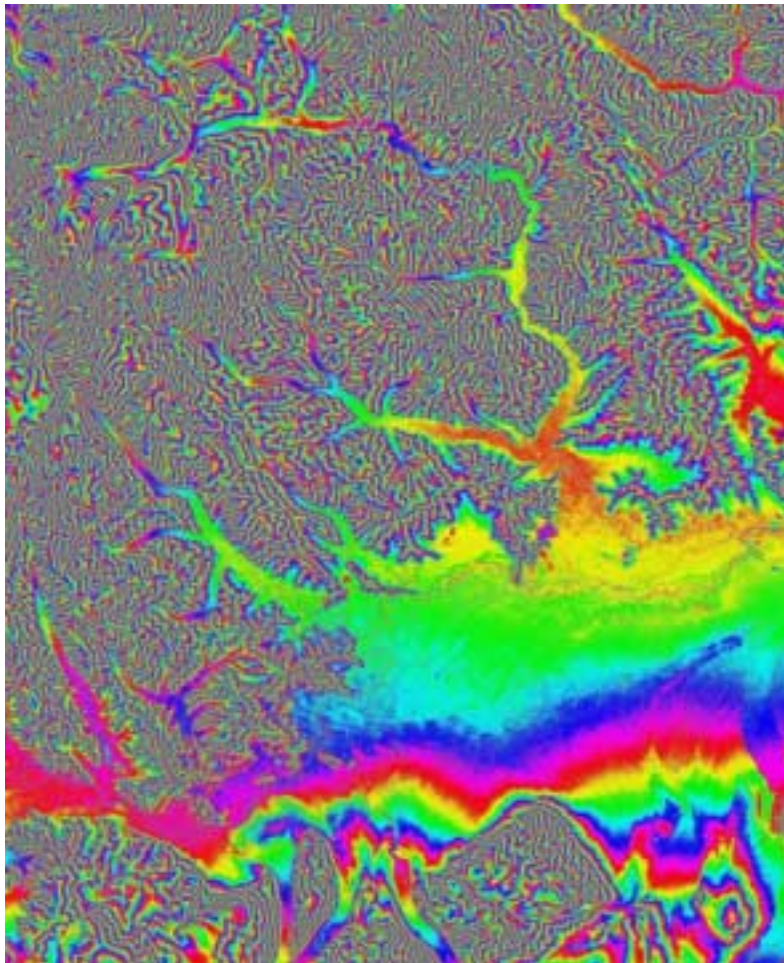
- multilooking of interferogram
- unwrapping with
 - snaphu (minimum cost flow algorithm)
 - escher (branch cut algorithm)
- unwrapped phase related to height

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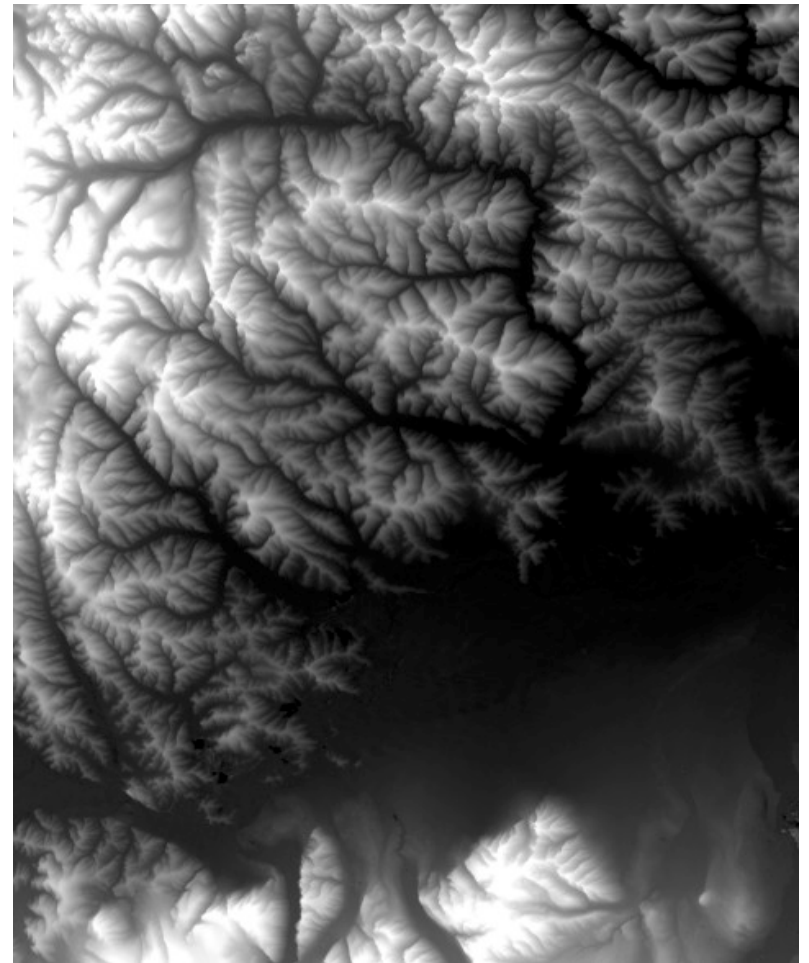


Phase unwrapping

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wrapped phase

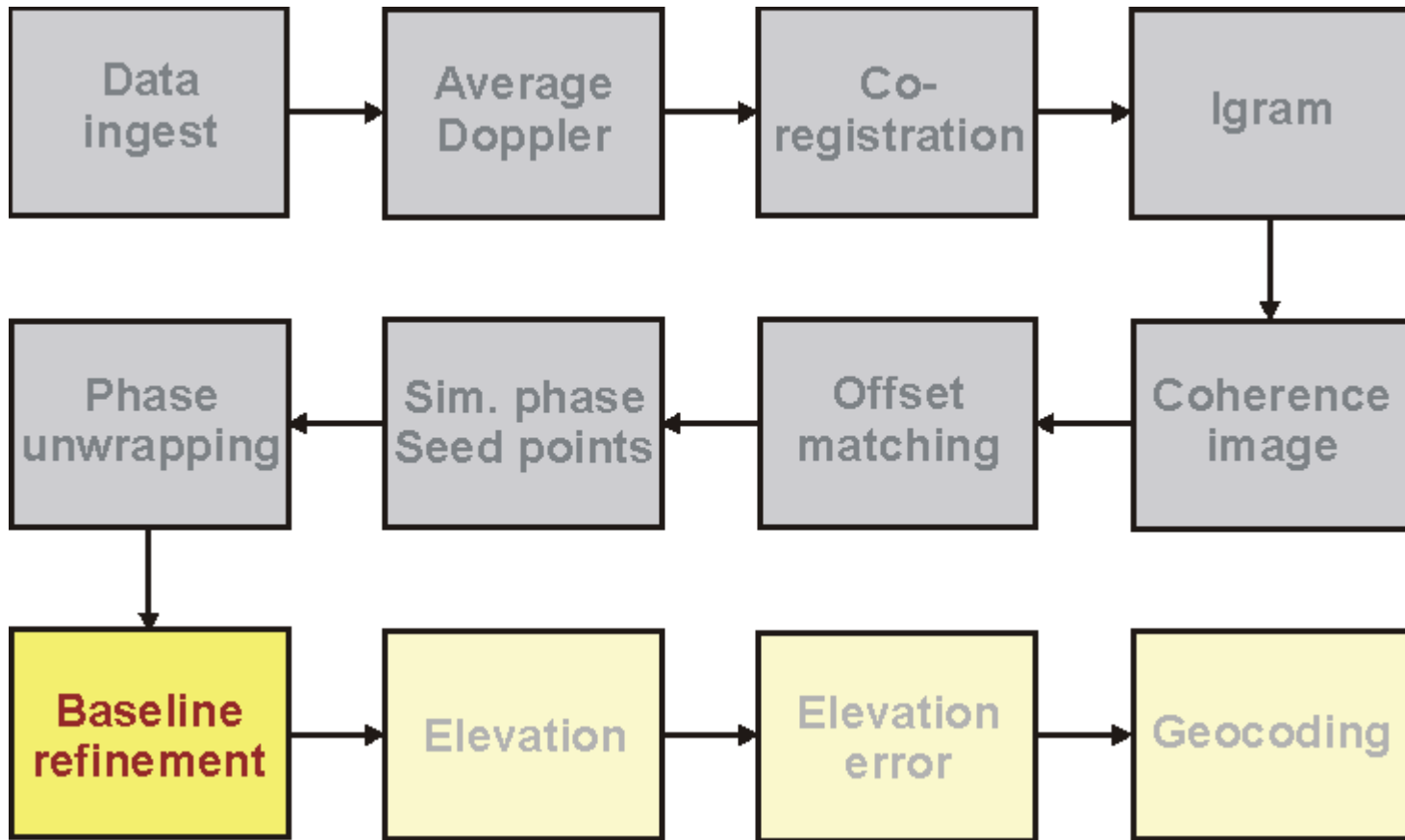


unwrapped phase



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Baseline refinement

- information used
 - unwrapped phase
 - baseline estimate
 - seed points
- iterative process

Bn: -61.829628, Δ : 5.643837, Bp: 19.505440, Δ : -2.099306

Bn: -61.527863, Δ : 5.565868, Bp: 19.777119, Δ : -2.117374

Bn: -61.549664, Δ : 5.693950, Bp: 19.776737, Δ : -2.112025

Bn: -61.550213, Δ : 5.695910, Bp: 19.776741, Δ : -2.111963

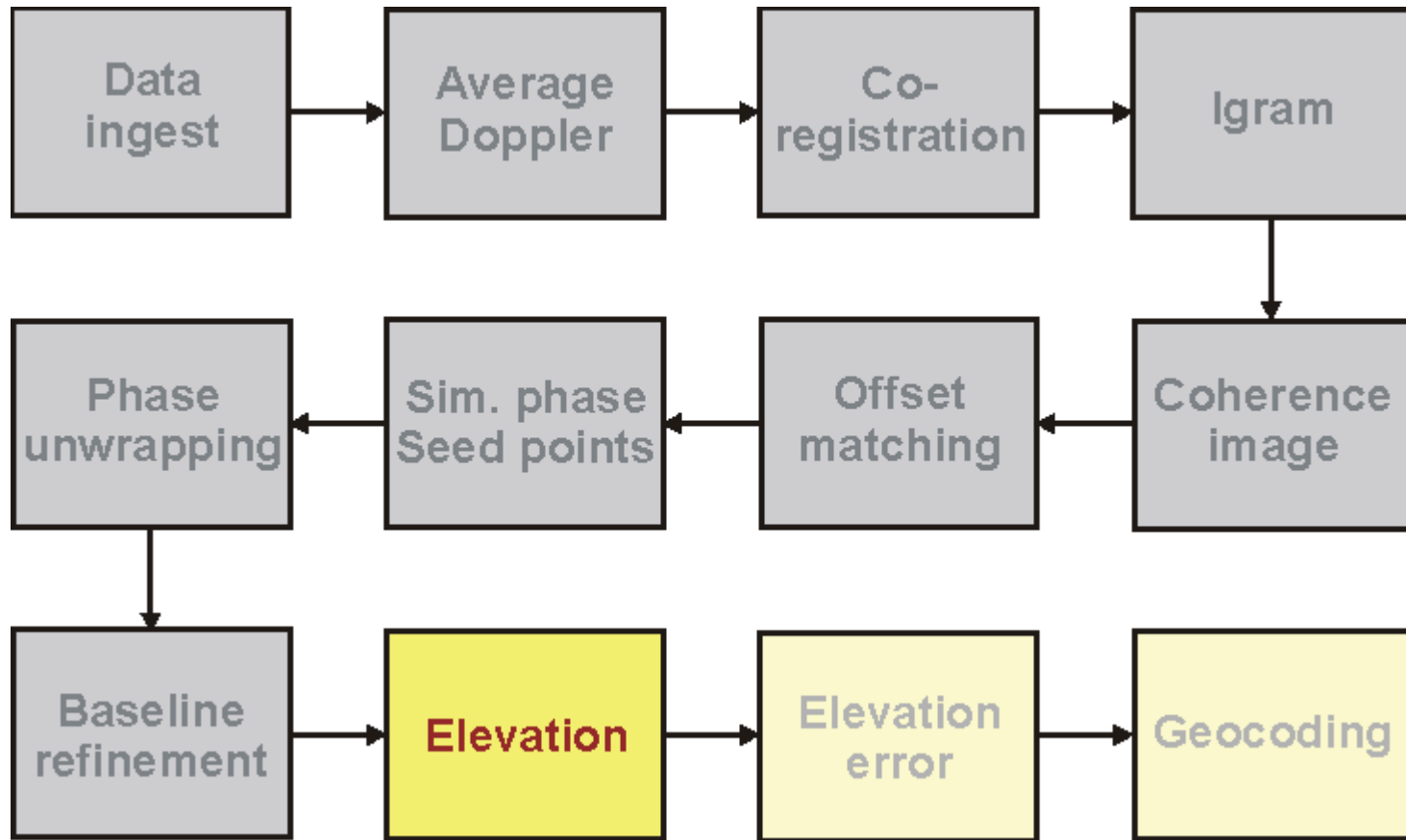
Bn: -61.550186, Δ : 5.695967, Bp: 19.776741, Δ : -2.111965

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InSAR processing

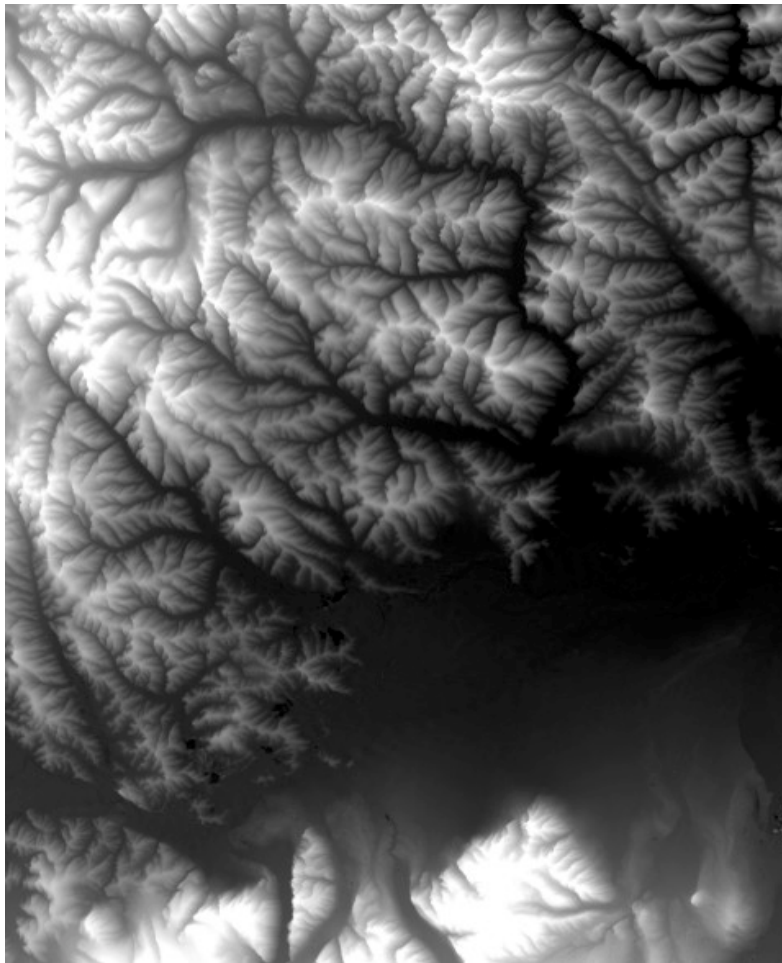
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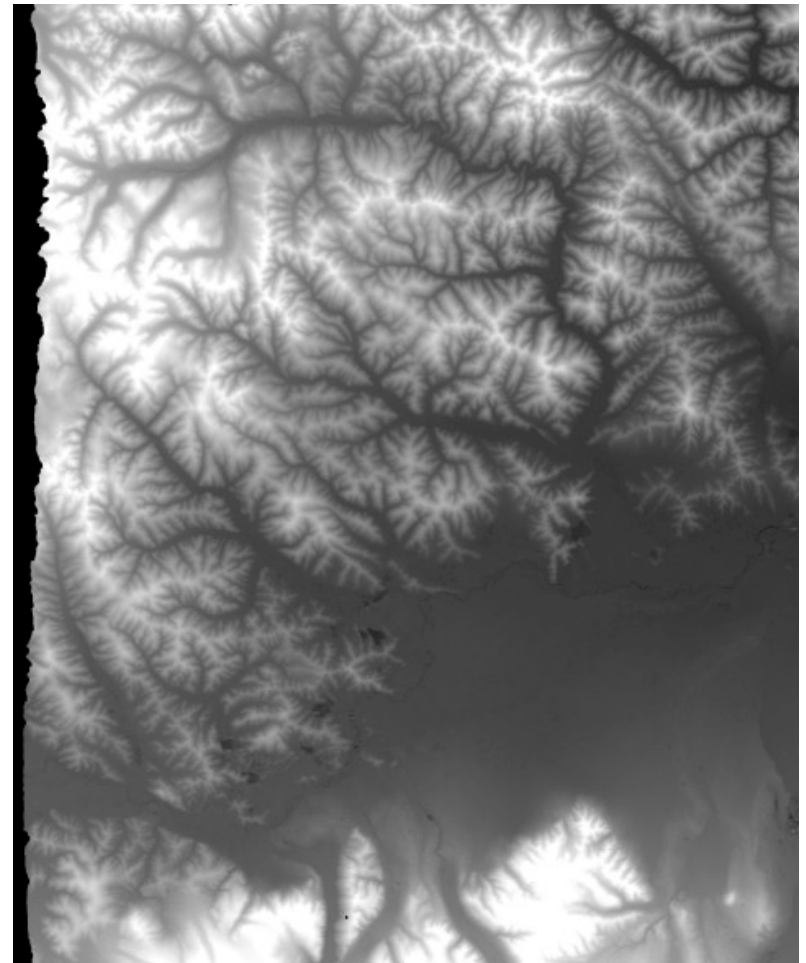


Elevation

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Slant range elevation

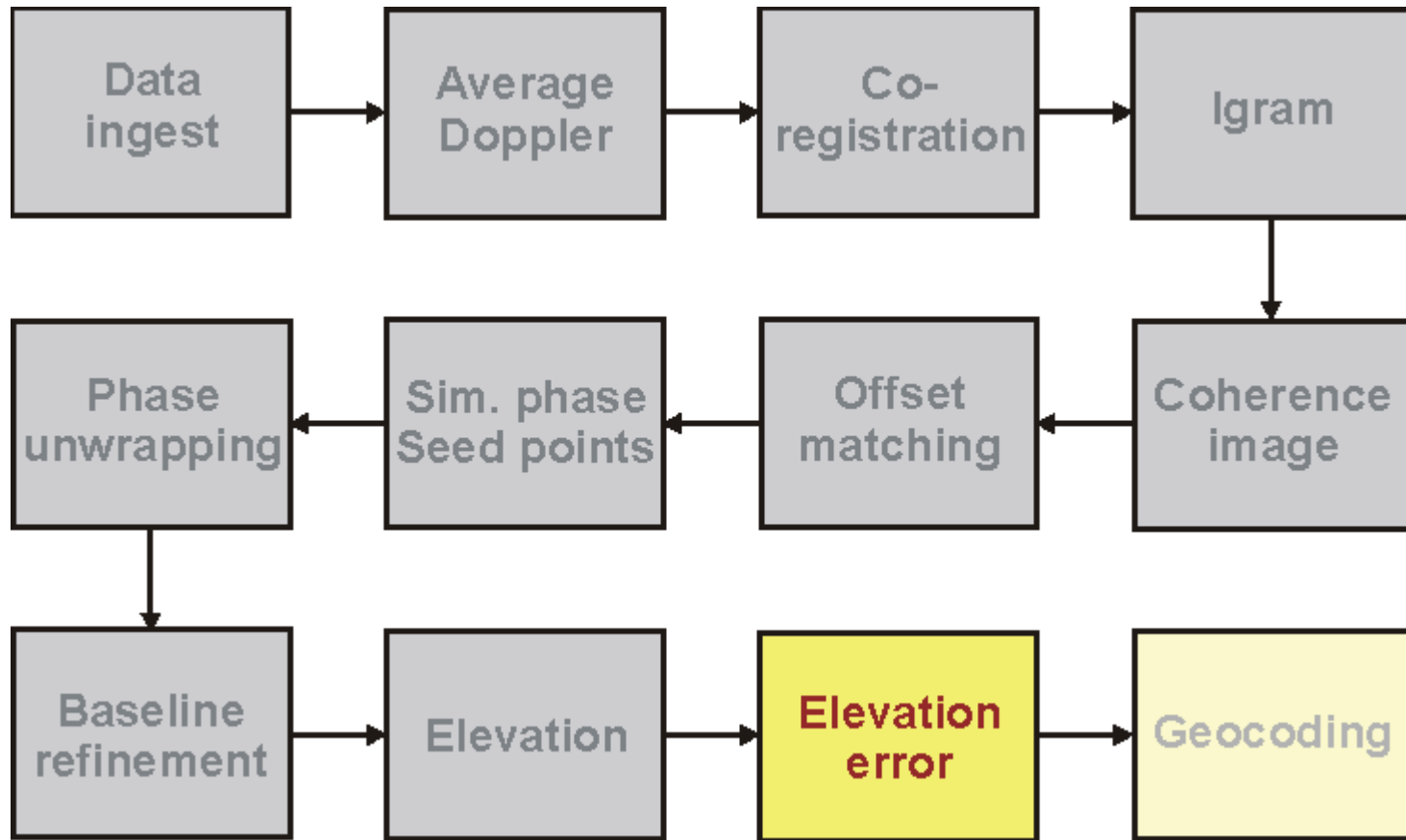


Ground range elevation



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Elevation error

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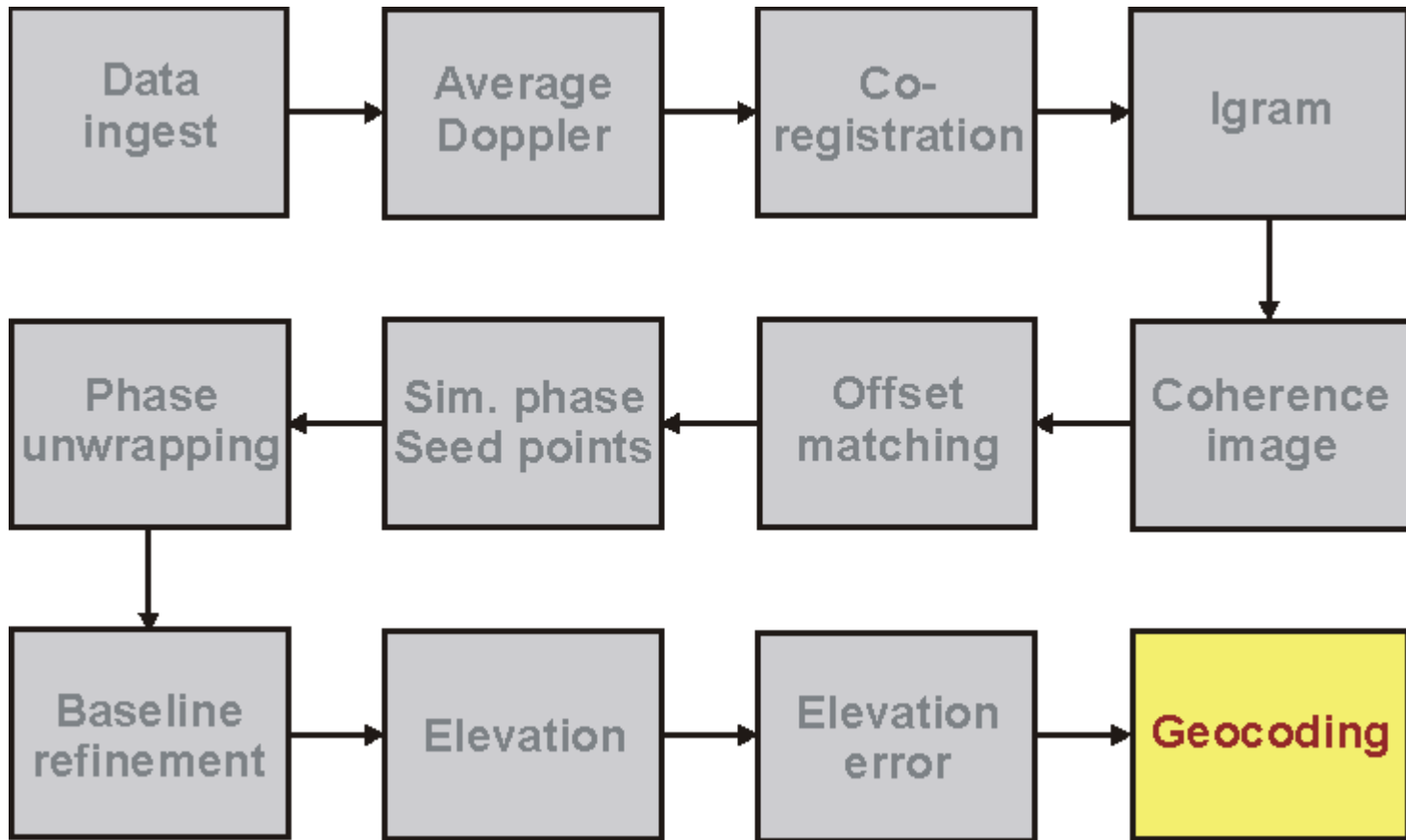


- estimate base on
 - initial height error estimate
 - baseline induced height
 - baseline
 - "flat earth" look deviation
 - coherence



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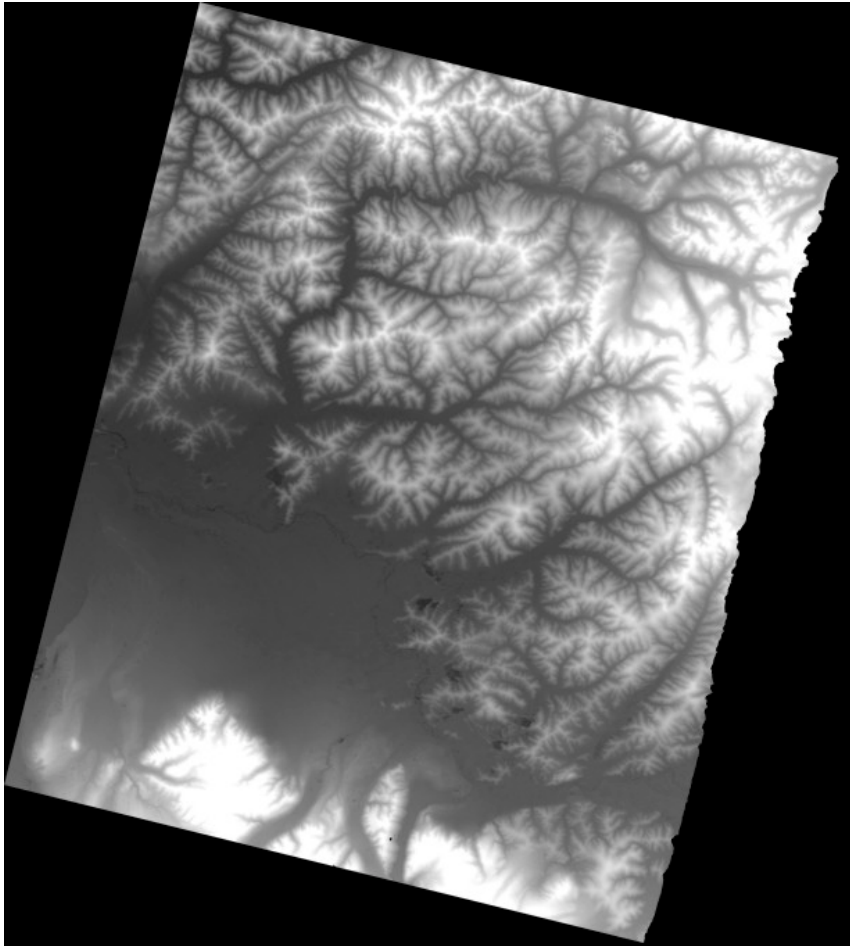
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Geocoding

- final product
- map projected
 - UTM
 - Albers
 - polar stereo

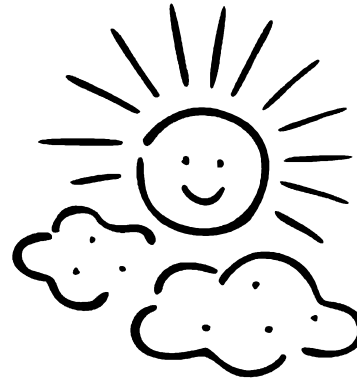


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Problems?

Talk to Rick !



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Questions

