



# Polarimetric SAR

## Applications and Calibration

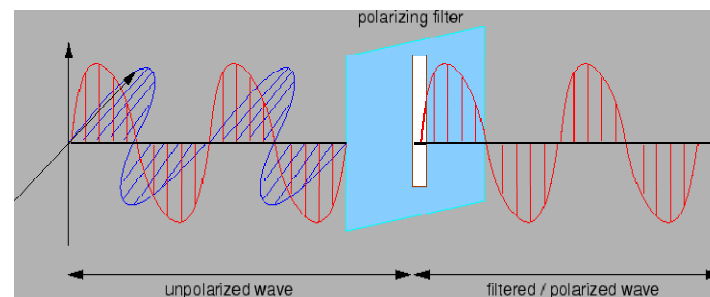
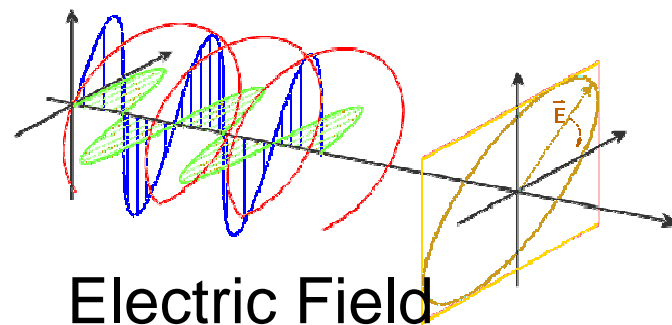


- **What is Polarimetry**
- **Why we care**
  - **Extract information of radar targets**
    - **Land use, Deforestation, Hydrology, Sea Ice, Oil Spills**
  - **Separate targets from background noise**
    - **Ship detection, Search and Rescue, Mineral Exploration**
- **Calibration of polarimetric SAR systems**
  - **Ground based calibrations**
  - **Space based calibrations**
  - **Faraday Rotation**



# What is Polarimetry?

- **Polarimetric information holds details of the scattering target.**
- **Discriminates between specific targets and background noise.**
- **Emerging science/art enabled by increased processing power**
- **Allows automated classification of images**



Polarizing Filter



# Radar Target

- Polarized radar pulse interacts with the scattering target
- Return signal received contains polarization information imparted by the target.
- Matrices describe the scattering target

$$\bar{S} = \begin{bmatrix} S_{HH} & S_{HV} \\ S_{VH} & S_{VV} \end{bmatrix}$$

Basic Scattering Matrix

$$E^{ire} = [S] E^{itr} = \begin{bmatrix} E_h^{re} \\ E_v^{re} \end{bmatrix} = \frac{e^{ik_0 r}}{r} \begin{bmatrix} S_{hh} & S_{hv} \\ S_{vh} & S_{vv} \end{bmatrix} \begin{bmatrix} E_h^{tr} \\ E_v^{tr} \end{bmatrix}$$

Jones Matrix


$$\frac{1}{r^2} \begin{bmatrix} S_{vv}^* S_{vv} & S_{vh}^* S_{vh} & S_{vh}^* S_{vv} & S_{vv}^* S_{vh} \\ S_{hv}^* S_{hv} & S_{hh}^* S_{hh} & S_{hh}^* S_{hv} & S_{hv}^* S_{hh} \\ S_{hv}^* S_{vv} & S_{hh}^* S_{vh} & S_{hh}^* S_{vv} & S_{hv}^* S_{vh} \\ S_{vv}^* S_{hv} & S_{vh}^* S_{hh} & S_{vh}^* S_{hv} & S_{vv}^* S_{hh} \end{bmatrix} \begin{bmatrix} |E_v^t|^2 \\ |E_h^t|^2 \\ E_h^t E_v^{t*} \\ E_v^t E_h^{t*} \end{bmatrix}$$


Stokes Matrix




# Stokes Matrix

$$\begin{bmatrix} g_0 \\ g_1 \\ g_2 \\ g_3 \end{bmatrix} = \begin{bmatrix} |E_v|^2 + |E_h|^2 \\ |E_v|^2 - |E_h|^2 \\ 2\Re(E_v^* E_h) \\ 2\Im(E_v^* E_h) \end{bmatrix} = \begin{bmatrix} |E_{v0}|^2 + |E_{h0}|^2 \\ |E_{v0}|^2 - |E_{h0}|^2 \\ 2E_{v0}E_{h0} \cos(\delta) \\ 2E_{v0}E_{h0} \sin(\delta) \end{bmatrix}$$

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 $g_0$  is the total power in the wave.
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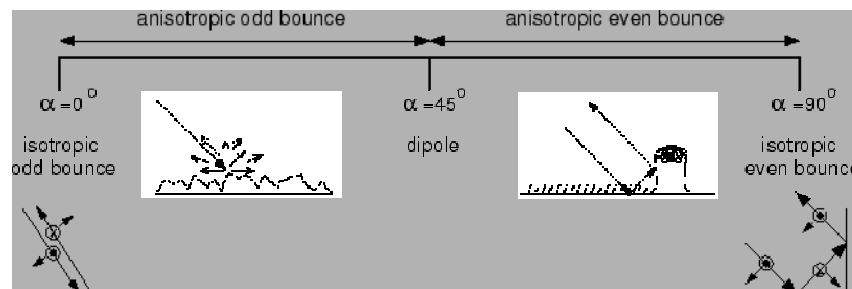
 $g_1$  is the difference in energy between the two orthogonal components of the wave.
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 $g_2$  and  $g_3$  jointly represent the phase difference between the real and imaginary cross terms

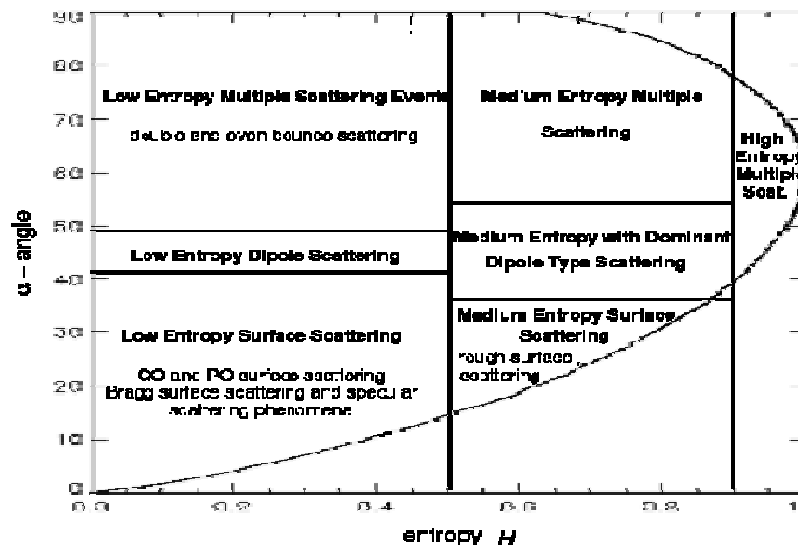


# Classification Terms

- $\alpha$  – Alpha Angle is an interpretation of type of scattering
- Anisotropy – Properties that deferrer according to direction of measurement
- Entropy,  $H$  - a measure of the randomness  
 Polarimetric response of terrain is dependent on several parameters: frequency, incidence angle, dielectric properties and dielectric geometry of the scene.



Alpha Angle & Anisotropy

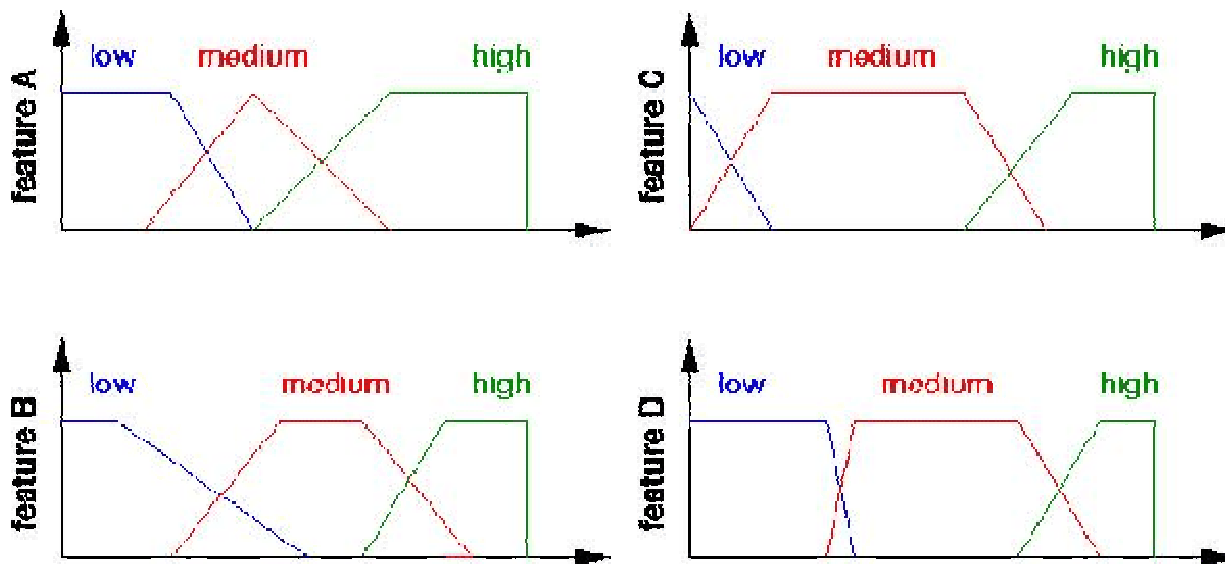


Entropy vs.  $\alpha$  Angle



# Polarimetry Witchcraft (Fuzzyfication)

- Fuzzy Logic is a multi-valued logic
  - Fuzzy sets can be defined by analyzing polarimetric response to known targets  
(Rule1: If A is low AND H is med AND  $\alpha$  high THEN Pixel is class 1)





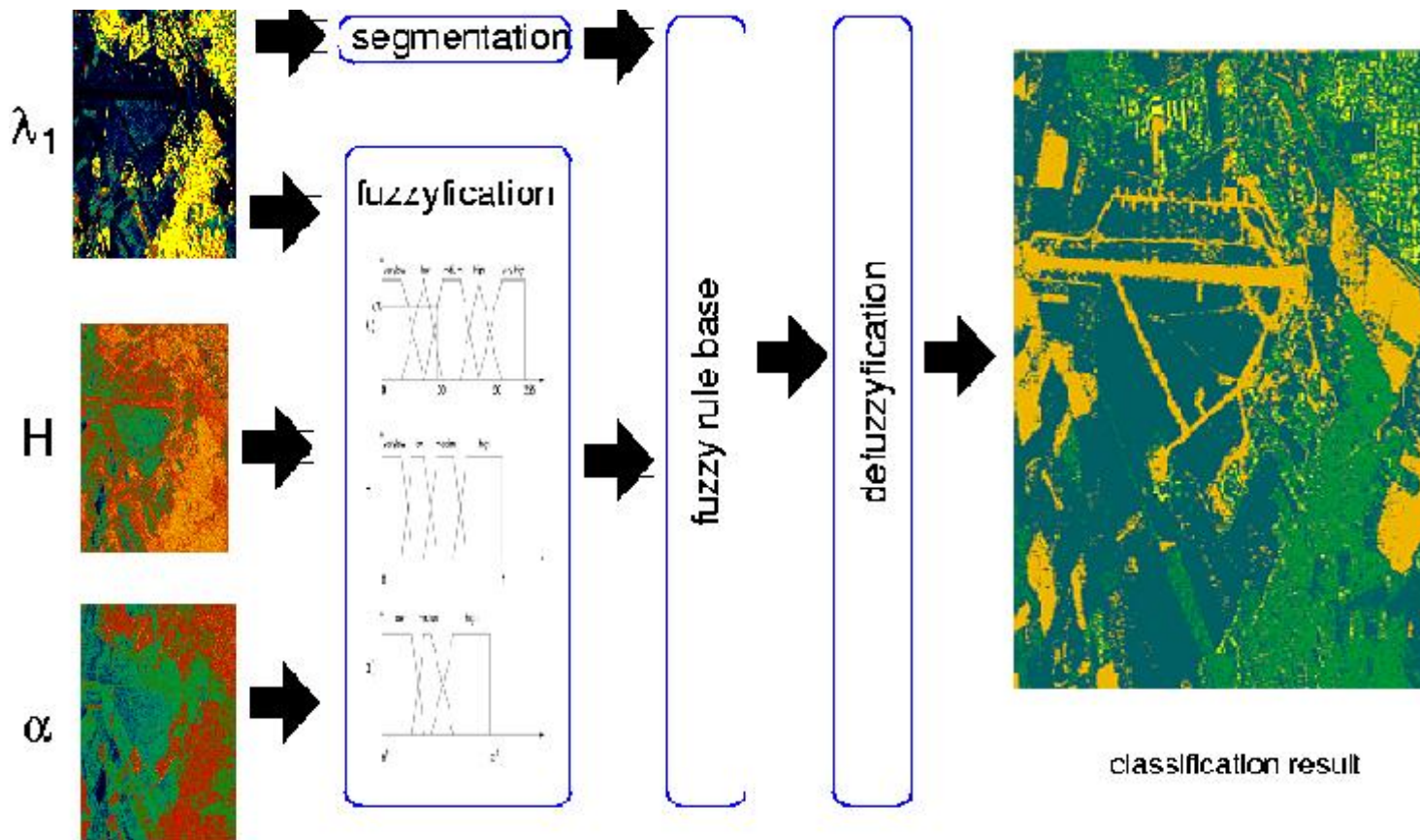
# Fuzzy Rule Base

$\lambda$	H	$\alpha$	<i>Decision</i>
Very High	Medium		Urban
High or Very High	Very Low	Medium/High	Urban
High	High		Forest
Medium	High	Medium/High	Forest
Medium	Medium	Medium/Low	Vegetation
Medium	Low or Very Low	Low	Vegetation
(Very) Low			Runway

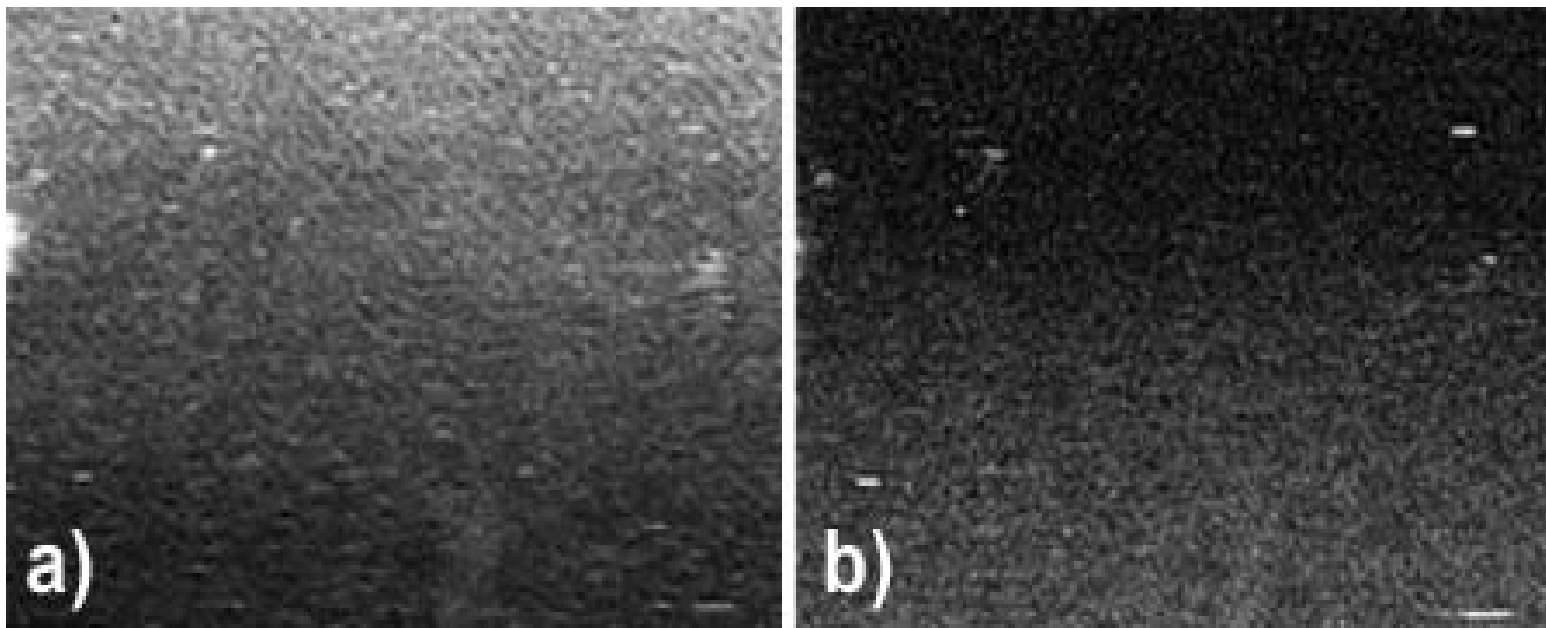




# Defuzzification (Feature Classification)



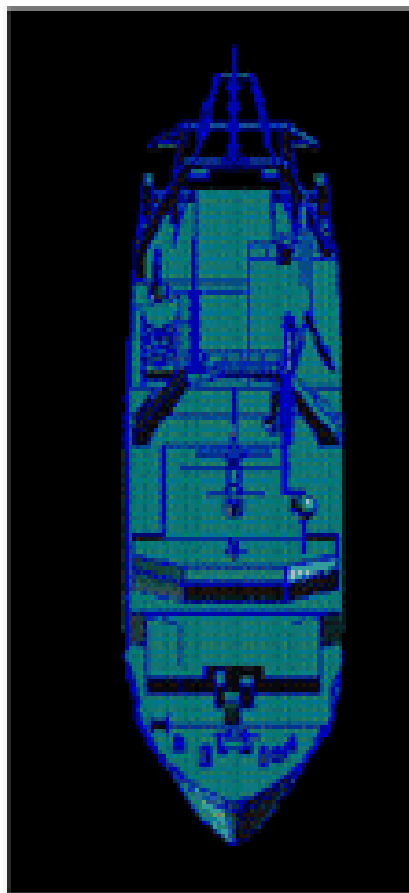
# Ship Tracking



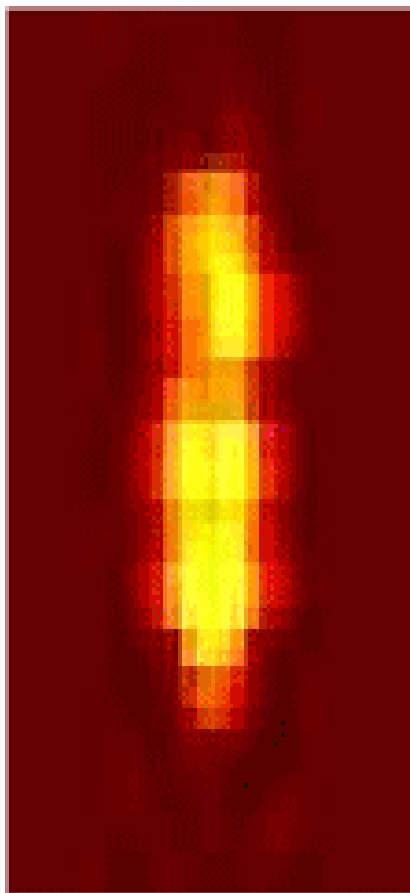
a) C-HH image b) corresponding polarization entropy image showing improved ship detection using the polarization entropy. Data from C-SAR on Canadian CV-580



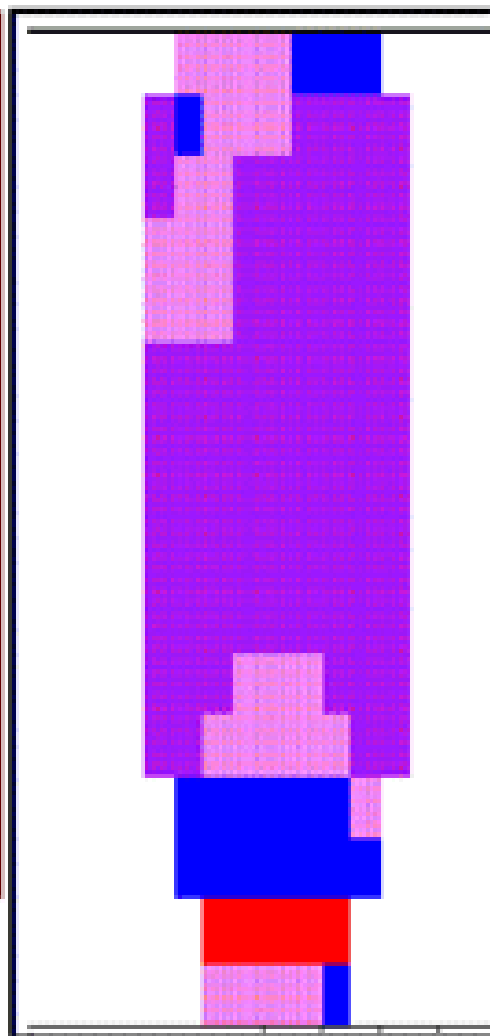
# Ship Identification



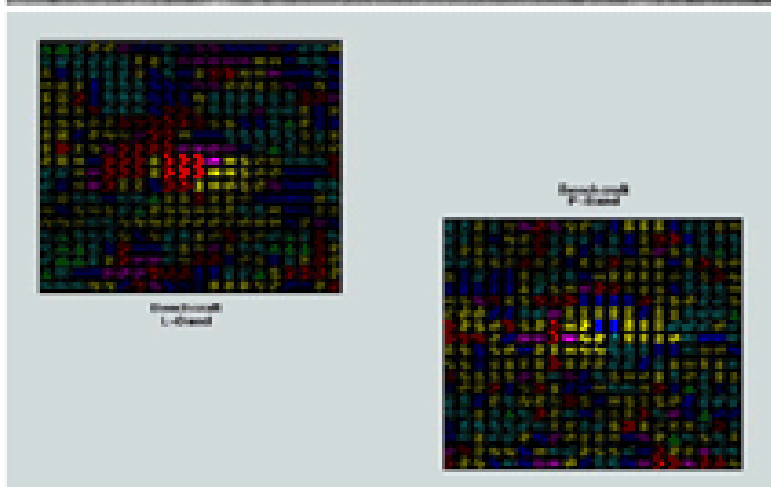
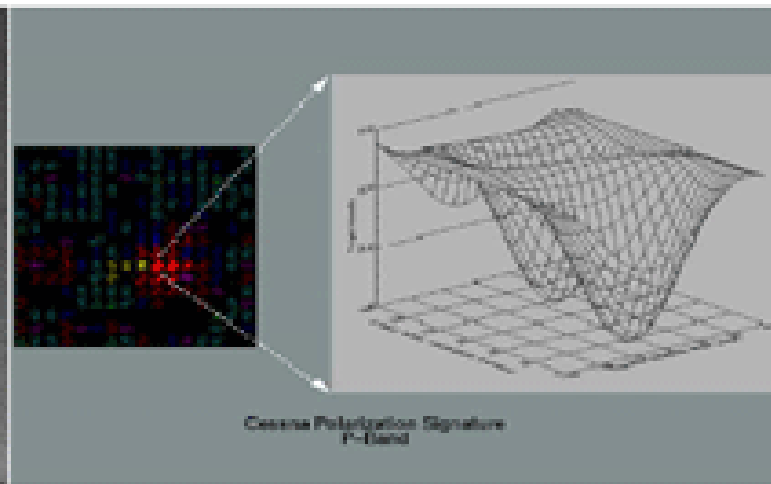
CAD Model



Simulated SAR Signature

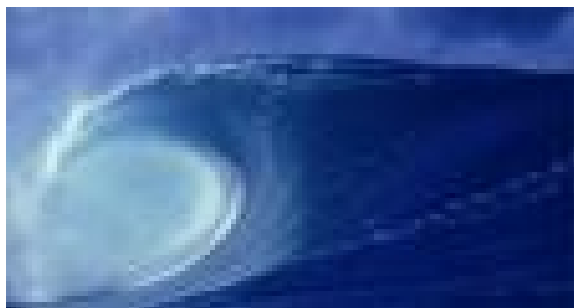


# Target Identification



	Tetrahedral natural world			
	Cylinder return weak in one direction			
	Dipole no return in one direction			
	1/4 wave second direction delayed			
	Dihedral			
	Higher Order dihedral with one direction attenuated			



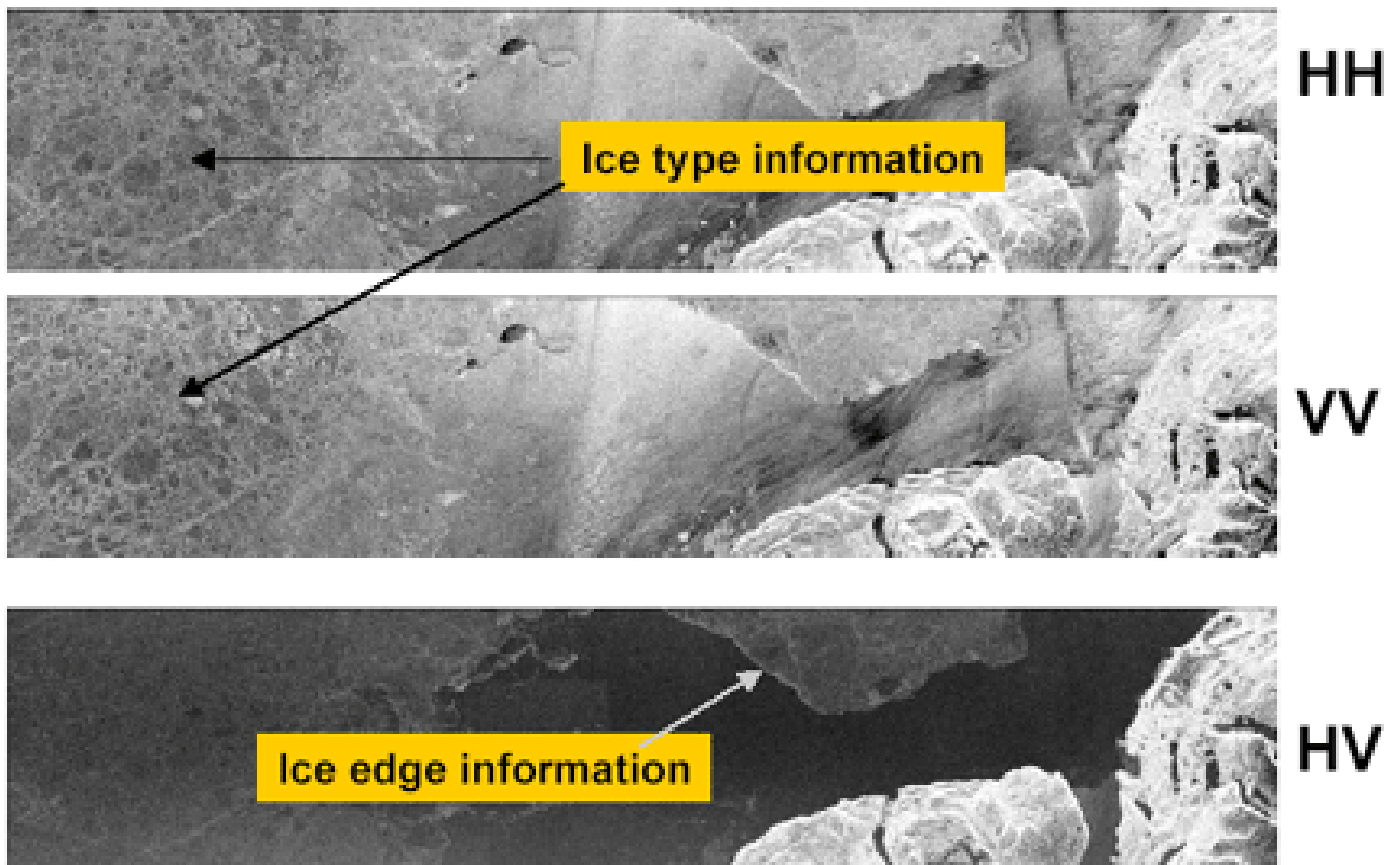


# Oceans

<b>Winds</b>	<b>VV</b>	<b>Better SNR for higher incidence angles benefits lower wind speed scenario's. Models use VV polarizations</b>
<b>Ship surveillance</b>	<b>VV - VH</b>	<b>VH gives point target info against dark background, VV should allow wake analysis for most incidence angles.</b>
	<b>HH - HV</b>	<b>Optimal ship detection based on the target to clutter ratio was:</b> <ul style="list-style-type: none"> <li>- HV for incidence angles &lt; 45 degrees</li> <li>- HH for incidence angles &gt; 45 degrees</li> </ul>
	<b>QUADPOL</b>	<b>Improve ship detection &amp; classification</b>
<b>Intertidal zone</b>	<b>HV</b>	<b>Enhance shoreline mapping</b>
	<b>Dual pol</b>	<b>Enhance coastal zone sensitivity mapping (tidal and near shore mapping)</b>



# Ice Classification



SIR-C Gulf of St. Lawrence



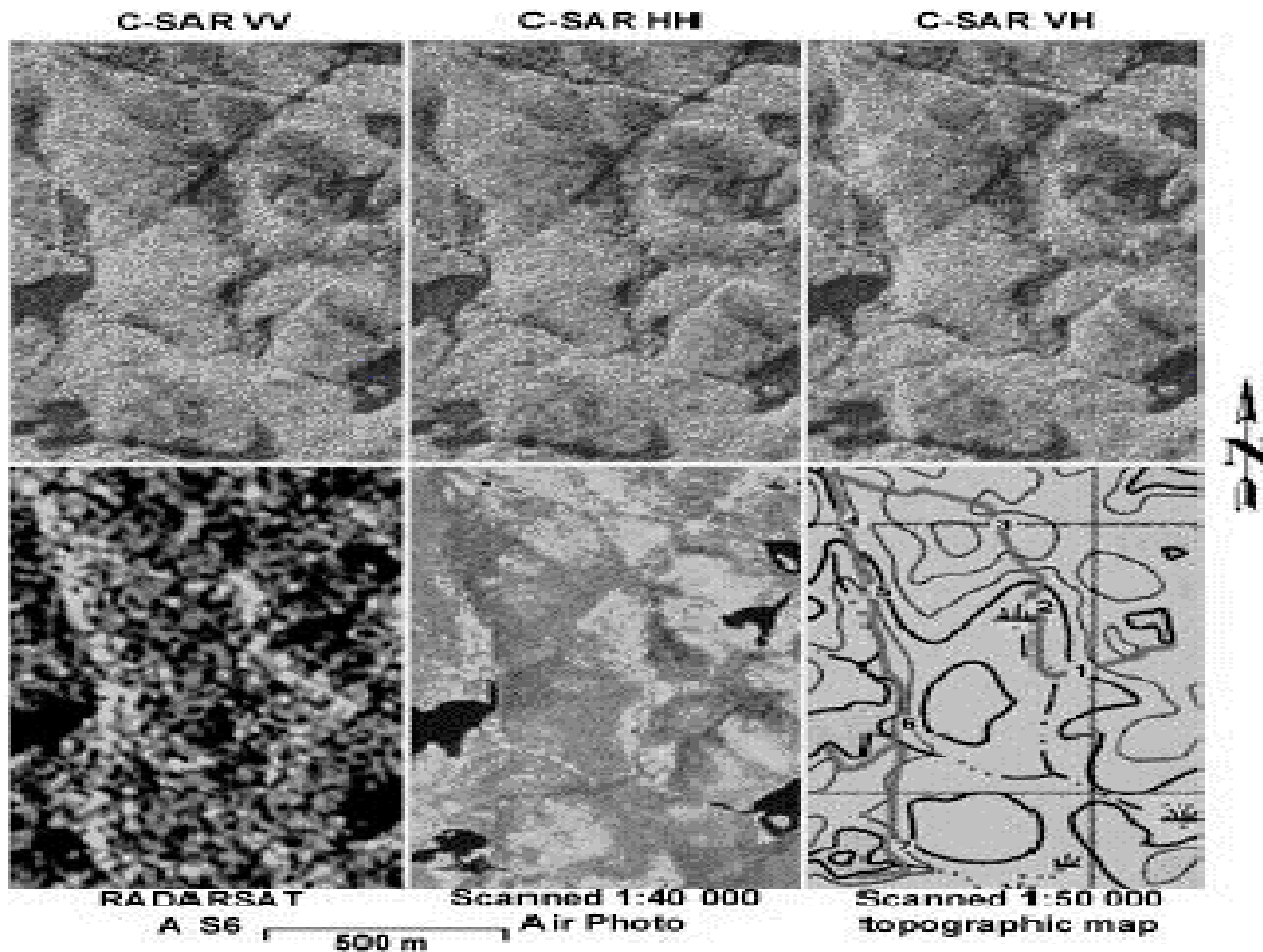


# Ice

Ice	Dual pol	HV improves distinction of ice edge.
	HH-HV	HH/HV ratio improve discrimination of multi-year from first year ice
	HH and VV	co-polarized ratio to distinguish between thin and new ice types from open water
	HV	Ice topography and structure, discrimination of smooth & deformed ice
Icebergs	HV	Detecting icebergs, particularly at steeper incidence angles & in higher seas



# Geologic Mapping







# Geology

Terrain Mapping	Ultra-fine	Permit more detailed mapping
	Dual pol & quad pol	Mapping surface deposits & rock units in vegetated terrains- different structural properties
	HV	Mapping recharge terrains in arid environments, HV provided better contrast than HH and VV
Structure	HV	Sensitive to extreme surface roughness or abrupt changes in relief. Bedrock fracture zones & fault scarps are highlighted.
Lithology	HH/HV or VV/HV	Better discrimination of different geological units





# Hydrology

Soil moisture	HH	HH is preferable to VV - greater penetration of vegetation cover
Wetlands	VV or HH	<p>Both are good for detecting flooding conditions, literature suggests:</p> <ul style="list-style-type: none"> <li>- Both for detecting flooding in dense marsh</li> <li>- VV better than HH for low density marsh</li> <li>- HH better than VV for flooded forest</li> <li>- Both for non-woody &amp; herbaceous wetlands</li> </ul>
	Quadpol	Improve the discrimination of wetland classes





# Disaster Management

<b>Floods</b>	<b>HH</b>	<b>Greatest difference at HH. Contrast increases with decreasing incidence angle</b>
<b>Geological Hazards</b>	<b>Ultrafine</b>	<b>More accurate mapping of landslides and earthquakes</b>
<b>Hurricanes</b>	<b>HH/HV or VV/VH</b>	<b>Co and cross-pol ratio may estimate rain rate- quantitative information on hurricane state and evolution.</b>
<b>Oil Spills</b>	<b>VV</b>	<b>Better contrast than either HH or HV</b>
	<b>Ultrafine</b>	<b>Enhance potential for tracking oil slicks and measure extent.</b>



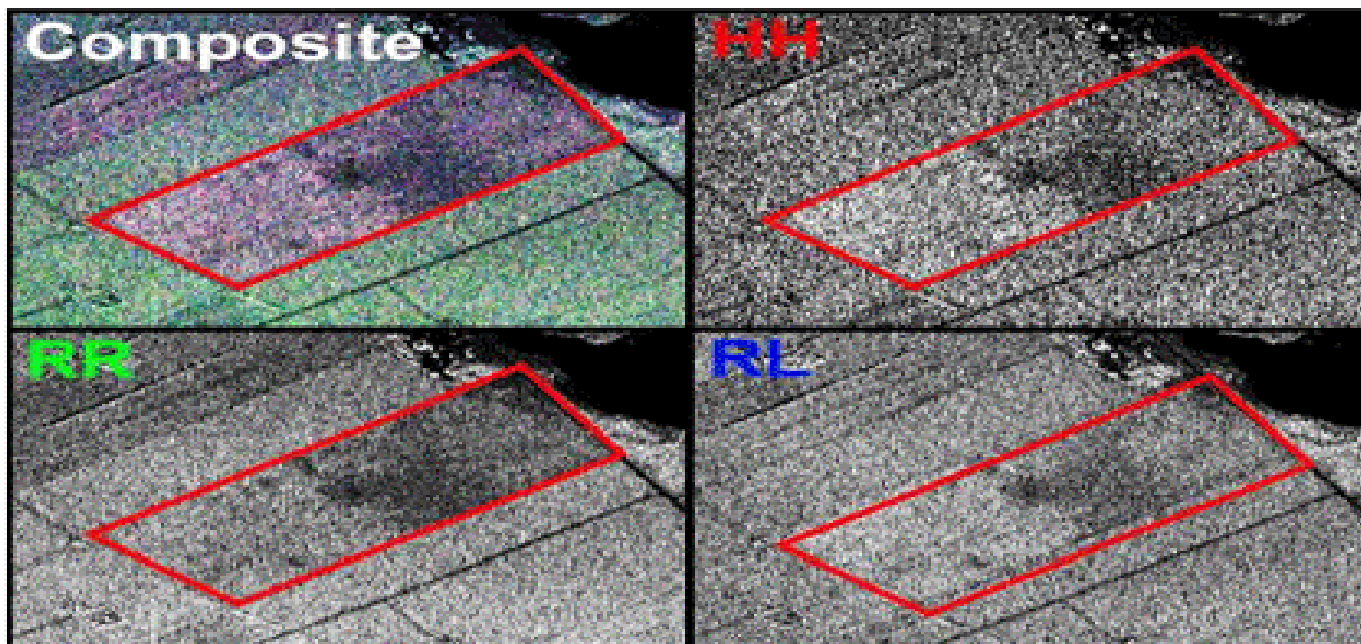


# Forestry

Clear cut mapping	Ultra fine	Increased accuracy of boundary placement
	HV or VH	Cross pol improves contrast (HH or VV) <u>Using dual pol (HH and HV or VV and VH) will further improve potential (Hoekman, 2001)</u>
	QUADPOL	<u>Promise for distinguishing clear cut from mature forest (Pairman, 2002)</u>
Fire-scar mapping	HV or VH	Best potential for burn mapping -sensitive to structural damage to forest canopy.
Biomass	HV or VH	Areas of low biomass can be monitored

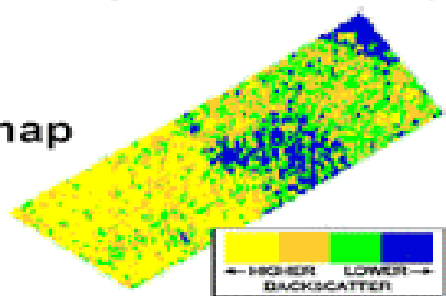


# Agricultural Assessment



CV-580 SAR Image acquired July 9, 1998, Ottawa, Canada

Classification map



after McNair;  
Images courtesy of CCRS





# Agriculture

Crop type	HH	Penetrate canopy- more information about the underlying soil condition
	HV	Good contrast of vegetation types with different canopy structures
	VV	Sensitive to crop structure- complementary information to HH and VV
Classification	Dual pol	Improvement in crop discrimination with two polarizations (45% with one, 78% with two)
Land use	HV	Differentiating vegetative surfaces from bare



# Methods of Calibration



## Ground Based – Minimize crosstalk

- Antenna Transmission and Receive Modules
- Gain and Internal Electronics (channel crosstalk, amplitude and phase balance, electronic noise, analog to digital converter)

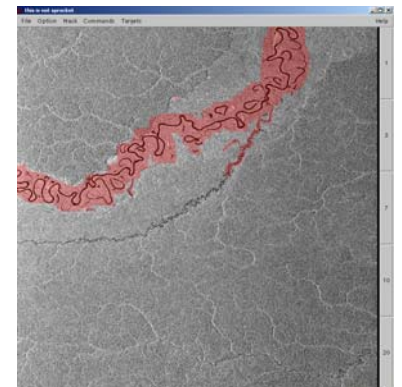
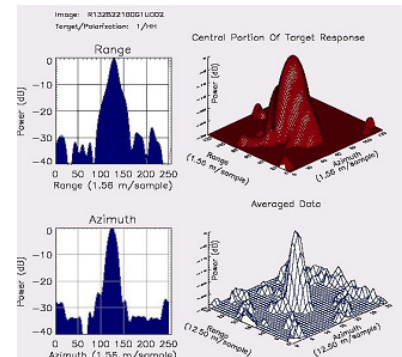


## Space Based – Internal Calibrations

- Calibration Ground Targets
  - Point targets – Geolocation, Resolution, PSLR
    - Transponders (PARCs), Corner Reflectors
  - Distributed Targets – Gain Patterns, Noise Level
    - Isotropic Volume Scatters, Dark Water Bodies
- Processor – Antenna Gain Pattern, Symmetrization of Polarization Cross Terms

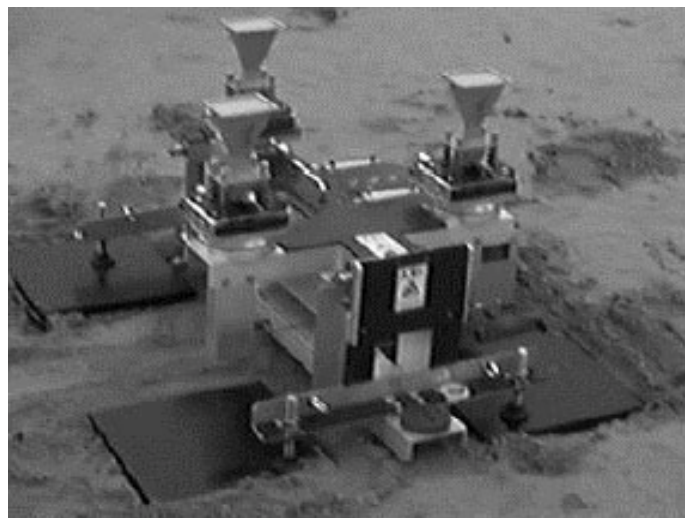
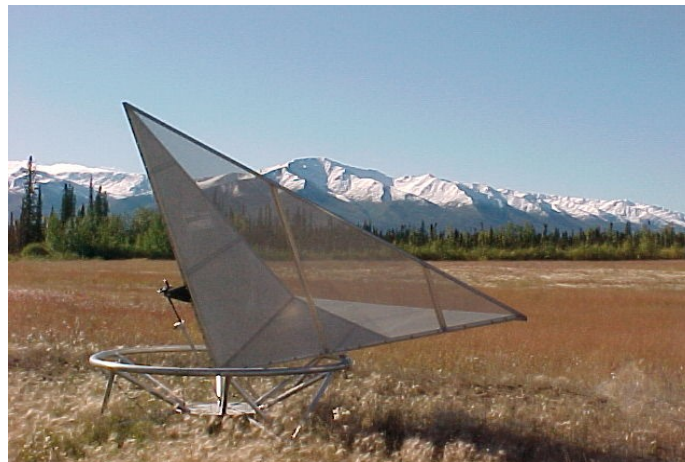


## Faraday Rotation – Correction



## Point Targets

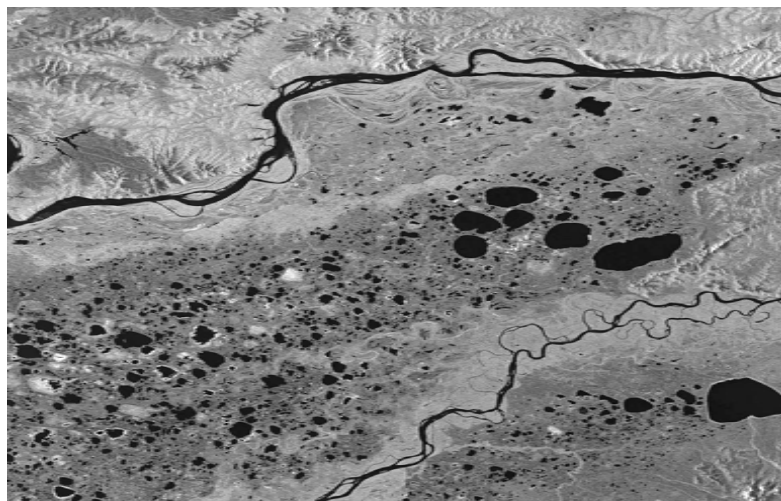
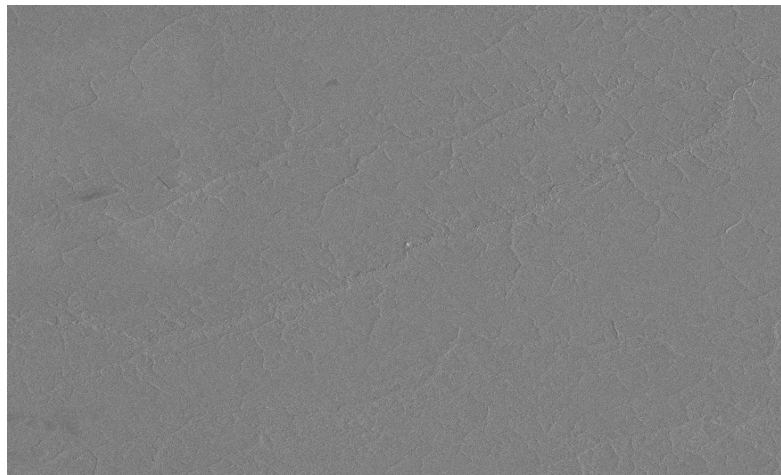
- **Passive Reflectors**
  - 2.45m Trihedral
  - 3 m Conical Dihedral
  
- **Polarimetric Active Radar Calibration Transponder**
  - Receives radar pulse
  - Adjusts phase & Polarization
  - Returns strong signal





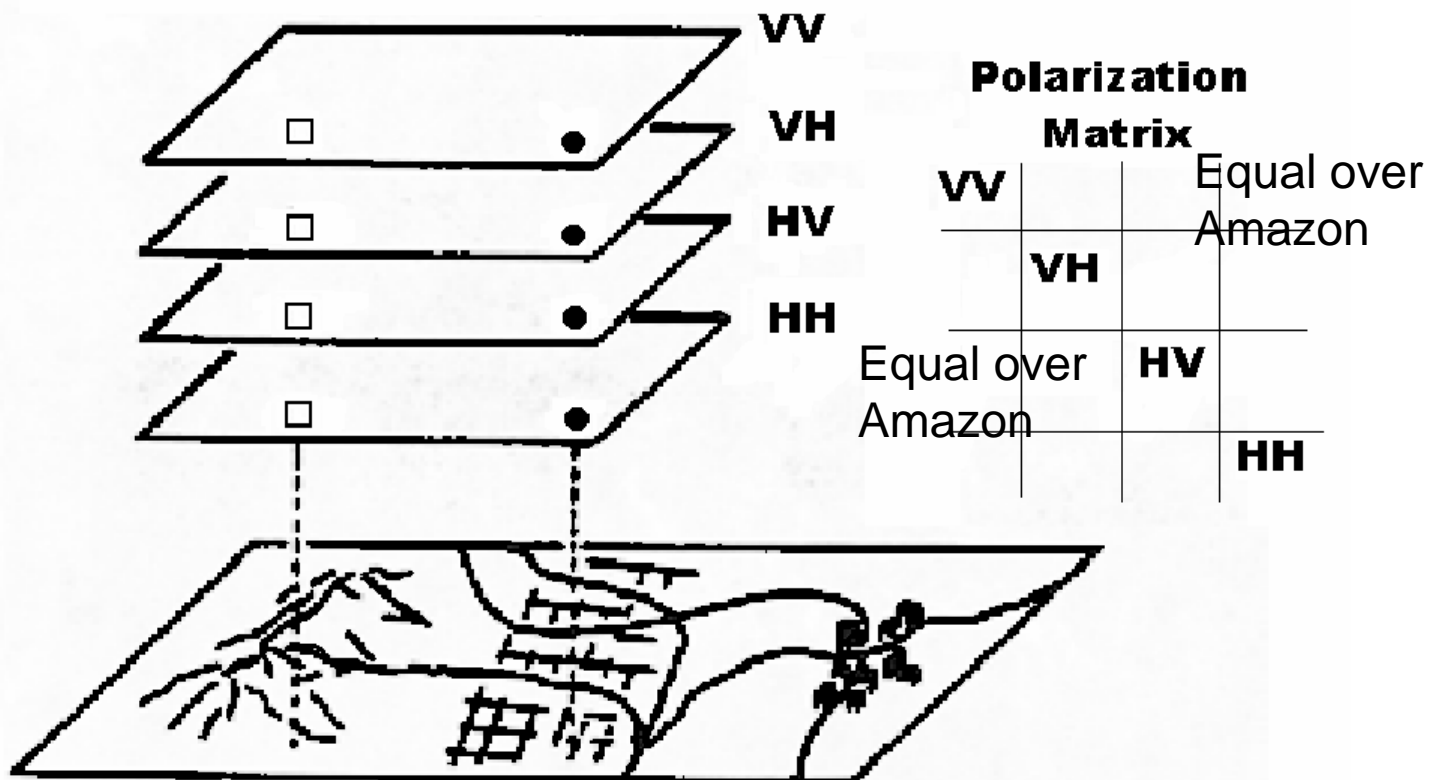
## Distributed Targets

- **Amazon Rainforest**
  - Isotropic Volume Scatter-  
Provide Homogeneous  
Calibration Image
  
- **Yukon – Kuskokwim**
  - Low backscatter Lakes-  
Provide a measure of the  
Noise Level

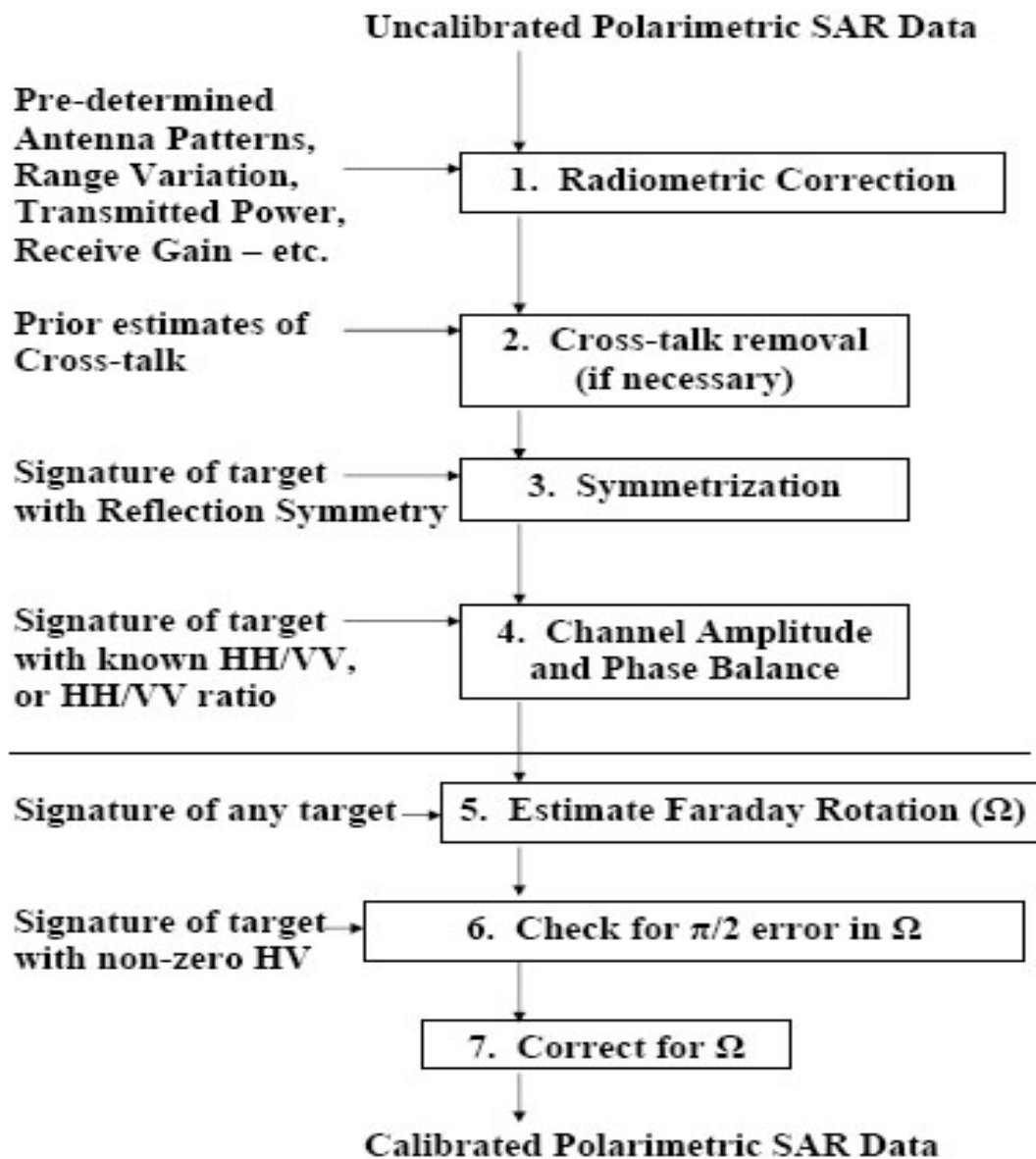


# Balancing Cross-terms (Symmetrization)

## Coregistered Images



# Processor Calibration

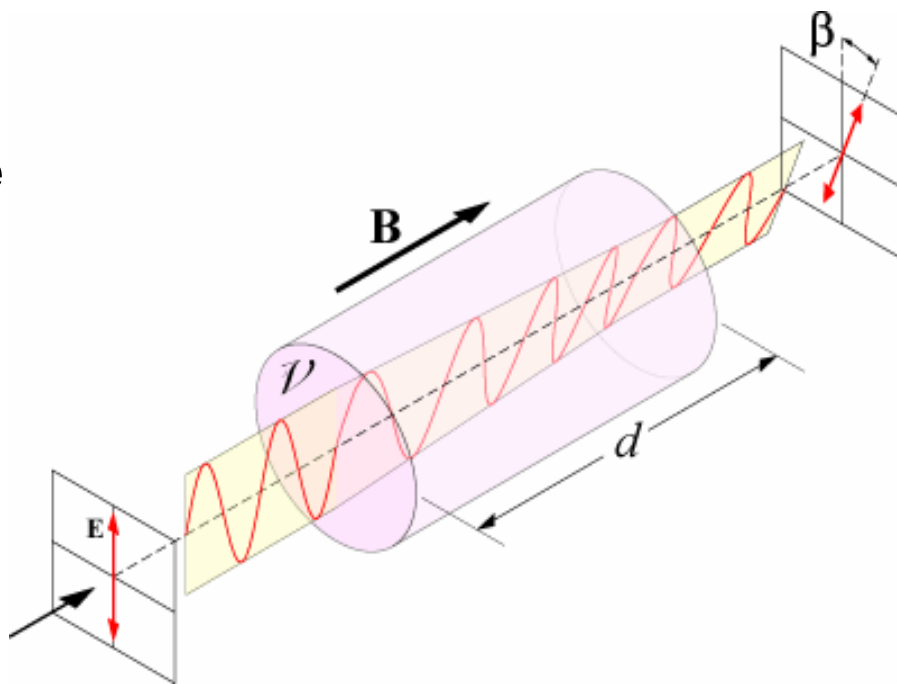


# Faraday Rotation

- Ionospheric Change of the Polarization Angle
- Effect is dependent on Solar Activity & Latitude
  - Strength of Field
  - Path length of signal
- Effect is dependent on Wavelength

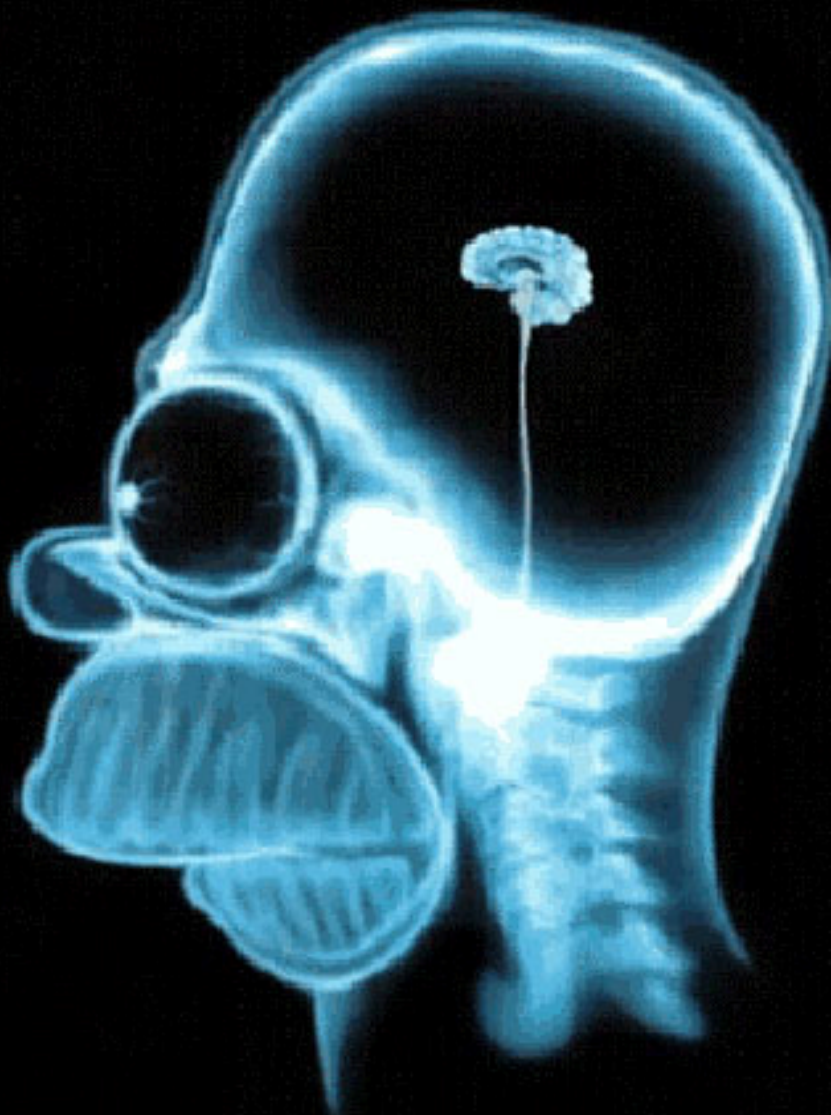
**Estimated Maximum:**

- X-Band (3 cm)  $\approx$  Small
- C-Band (6 cm)  $\approx 2.5^\circ$
- L-Band (24 cm)  $\approx 40^\circ$
- P-Band (68 cm)  $\approx 321^\circ$





# Questions ?



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